## Second Italian-Japanese Workshop

## GEOMETRIC PROPERTIES FOR PARABOLIC AND ELLIPTIC PDE's

Cortona (AR), June 2011, 20th-24th

A priori estimates and reduction principles for
quasilinear elliptic problems and applications (*)

Enzo Mitidieri Università di Trieste
${ }^{(*)}$ ) joint work with Lorenzo D’Ambrosio Università di Bari

## The organization of the seminar

- Introduction: Problems and motivations
- Some references
- Quasilinear weakly elliptic operators: Kato's inequality
- Reduction principles: the role of positive solutions
- Some classical applications of the reduction principles


## The organization of the seminar

- The role of the behavior at infinity of the nonlinearity
- Positivity and Liouville Theorems: Applications to

Schröedinger equations

A priori estimates of solutions of quasilinear elliptic equations has been a subject of fundamental and remarkable interest in recent years. For quasilinear elliptic problems, significant and interesting results are dealing with nonnegative solutions associated to nonlinearities that grow faster than the differential part.

Recently, Serrin [41] considered quasilinear coercive equations and inequalities with source term changing sign and proved some interesting Liouville theorems. These results (see also $[14,15]$ for related contributions) are consequence of appropriate a priori estimates on the possible solutions or on suitable functionals of them.

It is well known that when looking for Liouville theorems of non coercive nonlinear equations or inequalities, the fact that the nonlinearity has definite sign is of fundamental importance. This is because, in general, canonical examples of this type show that when the nonlinearity changes sign, the problem may posses infinitely many solutions with no a priori bound. A canonical example in this direction is the following,

$$
\begin{equation*}
-\Delta u=|u|^{q-1} u \quad \text { on } \mathbb{R}^{N} . \tag{1}
\end{equation*}
$$

Indeed, it is well known that if $1<q<\frac{N+2}{N-2}, N>2$, then (1) admits infinitely many radial solutions with increasing number of zeroes.

On the other hand, when the problem is coercive, then the situation may be completely different as the following striking result due to Brezis [6] shows.
Theorem (Brezis) Let $q>1$. If $u \in L_{\text {loc }}^{q}\left(\mathbb{R}^{N}\right)$ is a distributional solution of

$$
\begin{equation*}
\Delta u \geq|u|^{q-1} u \text { on } \mathbb{R}^{N}, \tag{2}
\end{equation*}
$$

then $u \leq 0$ a.e. on $\mathbb{R}^{N}$. In particular if equality holds in (2), then $u \equiv 0$ a.e. on $\mathbb{R}^{N}$.
It is worth pointing out that, besides the quite general functional framework, there are no assumptions on the behavior of the possible solutions of (2) at infinity.

Brezis's technique is based on a form of Kato's inequality $[24,6,2]$ and on a construction of a suitable Loewner-Nirenberg barrier function. See [27] and [26, 36].

Some generalizations of Brezis's result for quasilinear elliptic inequalities of second order have been obtained in $[14,15,16]$ and more recently in a series of papers by Farina and Serrin $[17,18]$ and Pucci and Serrin [38].

One common aspect in these recent contributions is that from the technical point of view, none of them use a form of Kato's inequality.

Thus one natural question is the extent to which Kato's inequality might be satisfied in the quasilinear case. A positive answer to this problem will allow to develop a general strategy for proving positivity type results as well as Liouville theorems for wide classes of quasilinear inequalities. This will bring together some aspects of qualitatively different problems, namely, coercive and non coercive quasilinear elliptic inequalities of second order. To get an idea of some preliminary results contained in this paper we mention the following special cases of Theorem 3.1 proved in the next section.

## Example 1. The $p$-Laplacian type operator.

Let $\Omega \subset \mathbb{R}^{N}$ be an open set. Let $f \in L_{\text {loc }}^{1}(\Omega)$ and let $u \in W_{\text {loc }}^{1, p}(\Omega)$ be a solution of the inequality,

$$
\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right) \geq f \quad \text { on } \Omega \text {. }
$$

Then,

$$
\operatorname{div}\left(\left|\nabla u^{+}\right|^{p-2} \nabla u^{+}\right) \geq \operatorname{sign}^{+}(u) f \quad \text { on } \Omega .
$$

## Example 2. The 1-Laplacian type operator.

Let $\Omega \subset \mathbb{R}^{N}$ be an open set. Let $f \in L_{\text {loc }}^{1}(\Omega)$ and let $u \in W_{\text {loc }}^{1,1}(\Omega)$ be a solution of the inequality,

$$
\operatorname{div}\left(|\nabla u|^{-1} \nabla u\right) \geq f \quad \text { on } \Omega \text {. }
$$

Then,

$$
\operatorname{div}\left(\left|\nabla u^{+}\right|^{-1} \nabla u^{+}\right) \geq \operatorname{sign}^{+}(u) f \quad \text { on } \Omega .
$$

Example 3. The mean curvature operator in non parametric form.
Let $\Omega \subset \mathbb{R}^{N}$ be an open set. Let $f \in L_{\text {loc }}^{1}(\Omega)$ and let $u \in W_{\text {loc }}^{1,2}(\Omega)$ be a solution of the inequality

$$
\operatorname{div}\left(\frac{\nabla u}{\sqrt{1+|\nabla u|^{2}}}\right) \geq f \quad \text { on } \Omega \text {. }
$$

Then,

$$
\operatorname{div}\left(\frac{\nabla u^{+}}{\sqrt{1+\left|\nabla u^{+}\right|^{2}}}\right) \geq \operatorname{sign}^{+}(u) f \quad \text { on } \Omega \text {. }
$$

The main goal of this seminar is to discuss some positivity results and Liouville Theorems for (3).

$$
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq f\left(x, u, \nabla_{L} u\right) \quad \text { on } \Omega \subset \mathbb{R}^{N}
$$

Here $\Omega \subset \mathbb{R}^{N}$ is an open set, $\mathscr{A}: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$ is a Caratheodory vector field, $f: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}$ is a Caratheodory function and $\nabla_{L}$ is a quite general vector field. Our study of (3) can be shortly described as follows.
i) Reduction of the problem (3) to an inequality that may posses only nonnegative solutions.
ii) Good a priori bounds of the possible nonnegative solutions of the reduced problem.
iii) Nonexistence of nonnegative solutions of the reduced problem.
iv) Nonexistence of nonnegative and changing sign solutions of (3)

In the above scheme, we shall see that point i) depends on the weak ellipticity of the differential operators. On the other hand, roughly speaking, ii) depends on the behavior of the nonlinearity at infinity. Notice that when dealing with non coercive problems, step ii) depends only on the behavior of the nonlinearity near zero. See [16].

Altogether the above considerations suggest the following natural problem for elliptic equations and inequalities.

Problem A: What kind of second order elliptic inequalities of type (3) on $\mathbb{R}^{N}$, admits only solutions of definite sign?

The possibility to exclude solutions changing sign is of fundamental importance when looking for Liouville theorems. We point out that an interesting consequence of the validity of Kato's inequality is that for a large class of differential inequalities associated
to coercive operators, the non existence of positive solutions implies that all possible solutions of the given problem must be of definite (negative) sign. In other words, the problem cannot have oscillatory solutions. This fact is obviously false if the problem is non coercive, see (1).

In this paper we will give an answer to the Problem A for inequalities of type (3) and illustrate some general implications. We shall call these consequences reduction principles. As we shall see during the course, these consequences imply some maximum and comparison principles, which are new in our general framework, and some of them are new even in the Euclidean setting (see Theorems 5.12 and 5.13).

Another point of interest is that our contribution shows that, when looking for Liouville theorems for coercive inequalities of type (3) with $f(x, t, \xi) t \geq 0$, the assumption that the possible solutions are nonnegative involves no loss of generality.

Consequenenty, to our hnorededge, most of the Liovilile thererens conceraing positire solutions proved in the liteature foc coercive problems, are indeed results on the non oscillatoy character of the posible saltitions of (3).

## References strictly related to this seminar

L. D'Ambrosio, E. Mitidieri, and S.I.Pohozaev, Representation formulae and inequalities for solutions of a class of second order partial differential equations, Trans. Amer. Math. Soc. 358 (2006), 893-910 .
L. D'Ambrosio and E. Mitidieri, Nonnegative solutions of some quasilinear elliptic inequalities and applications, Sb. Math. 201 (2010), 856-871.
L. D'Ambrosio and E. Mitidieri, A priori estimates, positivity results, and nonexistence theorems for quasilinear degenerate elliptic inequalities, Adv. Math. 224 (2010), 967-1020 .
A. Farina and J. Serrin, Entire solutions of completely coercive quasilinear elliptic equations, J. Differential Equations 250 (2011), 4367-4408.
A. Farina and J. Serrin, Entire solutions of completely coercive quasilinear elliptic equations II, J. Differential Equations 250 (2011), 4409-4436.

## References

[1] A. Ancona, On strong barriers and an inequality of Hardy for domains in $\mathbb{R}^{n}, J$. London Math. Soc. 34 (1986), 274-290.
[2] A. Ancona, Inégalité de Kato et inégalité de Kato jusqu'au bord. C. R. Math. Acad. Sci. Paris 346 (2008), 939-944.
[3] A. Baldi, A Non-existence problem for degenerate elliptic pde's, Comm. Partial Differential Equations 25 (2000), 1371-1398.
[4] M.F. Bidaut-Véron and S.I. Pohozaev, Nonexistence results and estimates for some nonlinear elliptic problems, J. Anal. Math. 84 (2001), 1-49.
[5] Y. Brennier, Extended Monge-Kantorovich Theory, in Optimal Transportation and Applications: Lectures given at the C.I.M.E. Summer School help in Martina Franca, L. A. Caffarelli and S. Salsa (eds.), Lecture Notes in Math. 1813, SpringerVerlag, 2003, 91-122.
[6] H. Brezis, Semilinear equations in $\mathbb{R}^{n}$ without condition at infinity, Appl. Math. Optimization 12 (1984), 271-282.
[7] R.D. Benguria, S. Lorca and C.S. Yarur, Nonexistence results for solutions of semilinear elliptic equations, Duke Math. J. 74 (1994), 615-634.
[8] A. Bonfiglioli, E. Lanconelli and F. Uguzzoni, Stratified Lie groups and potential theory for their sub-Laplacians. Springer Monographs in Mathematics. Springer, Berlin (2007).
[9] L. Capogna, D. Danielli and N. Garofalo, An Embedding Theorem and the Harnack inequality for nonlinear subelliptic equations, Comm. Partial Differential Equations 18 (1993), 1765-1794.
[10] T. Coulhon , I. Holopainen and L. Saloff-Coste, Harnack inequality and hyperbolicity for subelliptic p-Laplacians with applications to Picard type theorems, 15 Geom. Funct. Anal. 11 (2001), 1139-1191.
[11] L. Damascelli, Comparison theorems for some quasilinear degenerate elliptic operators and applications to symmetry and monotonicity results, Ann. Inst. H. Poincarè 15 (1998), 493-516.
[12] L. D'Ambrosio, Hardy-type inequalities related to degenerate elliptic differential operators, Ann. Scuola Norm. Sup. Pisa Cl. Sci. Ser. 5 IV (2005), 451-486.
[13] L. D'Ambrosio, Liouville theorems for anisotropic quasilinear inequalities Nonlinear Anal. 70 (2009), 2855-2869.
[14] L. D'Ambrosio and E. Mitidieri. Positivity property of solutions of some quasilinear elliptic inequalities, Functional Analysis and Evolution Equations, The Günter Lumer Volume, Birkhäuser, (2008), 147-156.
[15] L. D'Ambrosio and E. Mitidieri, Nonnegative solutions of some quasilinear elliptic inequalities and applications, Sb. Math. 201 (2010), 856-871.
[16] L. D'Ambrosio and E. Mitidieri, A priori estimates, positivity results, and nonexistence theorems for quasilinear degenerate elliptic inequalities, Adv. Math. 224 (2010), 967-1020.
[17] A. Farina and J. Serrin, Entire solutions of completely coercive quasilinear elliptic equations, J. Differential Equations 250 (2011), 4367-4408.
[18] A. Farina and J. Serrin, Entire solutions of completely coercive quasilinear elliptic equations II, J. Differential Equations 250 (2011), 4409-4436.
[19] G.B. Folland and E.M. Stein, Hardy Spaces on Homogeneous Groups, Mathematical Notes vol. 28 Princeton University Press, Princeton, NJ, 1982, 1-46.
[20] R. Filippucci, P. Pucci and M. Rigoli, Non-existence of entire solutions of degenerate elliptic inequalities with weights, Arch. Ration. Mech. Anal. 188 (2008), 155-179.
[21] G.B. Folland, Subelliptic estimates and function spaces on nilpotent Lie groups,
[22] G.B. Folland and E.M. Stein, Hardy spaces on homogeneous groups, Mathematical Notes 28. Princeton University Press, Princeton, N.J. (1982).
[23] P.C. Greiner, A fundamental solution for a nonelliptic partial differential operator, Canad. J. Math. 31 (1979), 1107-1120.
[24] T. Kato, Schr̈oedinger operators with singular potentials, Israel J. Math. 13 (1972), 135-148.
[25] J. Kinnunen and R. Korte, Characterizations for the Hardy inequality, in "Around the research of Vladimir Maz'ya. I", Int. Math. Ser. (N. Y.) 11, Springer, New York, 2010, 239-254.
[26] J.B. Keller, On solutions of $\Delta u=f(u)$, Commun. Pure Appl. Math. 10 (1957), 503-510.
[27] C. Loewner and L. Nirenberg, Partial differential equations invariant under conformal or projective transformations, Contribution to Analysis, Academic Press (1974), 503-510.
[28] M. Magliaro, L. Mari, P. Mastrolia, and M. Rigoli, Keller-Osserman type conditions for differential inequalities with gradient terms on the Heisenberg group, J. Differential Equations 250 (2011), 2643-2670.
[29] J. Maly and W.P. Ziemer, Fine Regularity of Solutions of Elliptic Differential Equations, Mathematical Surveys and Monographs, AMS 1997.
[30] M. Marcus, V. Mizel and Y. Pinchover, On the best constant for Hardy's inequality in $\mathbb{R}^{N}$, Trans. Amer. Math. Soc. 350 (1998), 3237-3255.
[31] E. Mitidieri and S.I. Pohozaev, Non Existence of Positive Solutions for Quasilinear Elliptic Problems on $\mathbb{R}^{\mathbb{N}}$, Tr. Mat. Inst. Steklova 227 (1999), 192-222.
[32] E. Mitidieri and S.I. Pohozaev, A priori estimates and the absence of solutions of nonlinear partial differential equations and inequalities, Tr. Mat. Inst. Steklova 234 (2001), 1-384.
[33] Y. Naito and H. Usami, Entire solutions of the inequality $\operatorname{div}(A(|D u|) D u) \geq f(u)$, Math. Z. 225 (1997), 167-175.
[34] W.-M. Ni and J. Serrin, Non-existence theorems for quasilinear partial differential equations, Supplemento di Rendiconti Circolo Matematico di Palermo 8 (1985), 171185.
[35] W.-M. Ni and J. Serrin, Existence and non-existence theorems for ground states of quasilinear partial differential equations. The anomalous case, Rome, Acc. Naz. dei Lincei, Atti dei Convegni 77 (1986), 231-257.
[36] R. Osserman, On the inequality $\Delta u \geq f(u)$, Pac. J. Math. 7 (1957), 1641-1647.
[37] P. Pucci and J. Serrin, The Strong Maximum Principle, "Progress in Nonlinear Differential Equations and their Applications", 73, Birkhauser Publ., Switzerland, 2007, X, 234 pages.
[38] P. Pucci and J. Serrin, A remark on entire solutions of quasilinear elliptic equations, J. Differential Equations 250 (2011), 675-689.
[39] P. Rosenau, Tempered Diffusion: A Transport Process with Propagating Front and Inertial Delay, Phys. Review A 46 (1992), 7371-7374.
[40] J. Serrin, Local behavior of solutions of quasi-linear equations, Acta Math. 111 (1964), 247-302.
[41] J. Serrin, Entire solutions of quasilinear elliptic equations, J. Math. Anal. Appl. 352 (2009), 3-14.

## 1 Notations and definitions

In this paper $\nabla$ and $|\cdot|$ stand respectively for the usual gradient in $\mathbb{R}^{N}$ and the Euclidean norm. $\Omega \subset \mathbb{R}^{N}$ open. Let $\mu \in \mathscr{C}\left(\mathbb{R}^{N} ; \mathbb{R}^{l}\right)$ be a matrix $\mu:=\left(\mu_{i j}\right), i=1, \ldots, l, j=1, \ldots, N$ and assume that for any $i=1, \ldots, l, j=1, \ldots, N$ the derivative $\frac{\partial}{\partial x_{j}} \mu_{i j} \in \mathscr{C}(\Omega)$. For $i=1, \ldots, l$, let $X_{i}$ and its formal adjoint $X_{i}^{*}$ be defined as

$$
\begin{equation*}
X_{i}:=\sum_{j=1}^{N} \mu_{i j}(\xi) \frac{\partial}{\partial \xi_{j}}, \quad X_{i}^{*}:=-\sum_{j=1}^{N} \frac{\partial}{\partial \xi_{j}}\left(\mu_{i j}(\xi) \cdot\right) \tag{4}
\end{equation*}
$$

and let $\nabla_{L}$ be the vector field defined by

$$
\nabla_{L}:=\left(X_{1}, \ldots, X_{l}\right)^{T}=\mu \nabla
$$

and

$$
\nabla_{L}^{*}:=\left(X_{1}^{*}, \ldots, X_{l}^{*}\right)^{T}
$$

For any vector field $h=\left(h_{1}, \ldots, h_{l}\right)^{T} \in \mathscr{C}^{1}\left(\Omega, \mathbb{R}^{l}\right)$, we shall use the following notation $\operatorname{div}_{L}(h):=\operatorname{div}\left(\mu^{T} h\right)$, that is

$$
\operatorname{div}_{L}(h)=-\sum_{i=1}^{l} X_{i}^{*} h_{i}=-\nabla_{L}^{*} \cdot h
$$

Examples of vector fields, which we are interested in, are the usual gradient acting on $l(\leq N)$ variables (see Example B.1), vector fields related to Bouendi-Grushin operator (see Example B.2), Heisenberg-Kohn sub-Laplacian (see Example B.3), Heisenberg-Greiner operator (see Example B.4), sub-Laplacian on Carnot Groups (see Appendix A). Another motivation for considering these kind of operators is the following. Let $A=\left(a_{i j}(x)\right)_{1 \leq i, j \leq N}$ be a matrix with continuous entries. Consider the linear operator $L u:=\operatorname{div}(A(x) \nabla u)$. Assume that $A$ is symmetric and positive semidefinite (that is $a_{i j}=a_{j i}$ and $A(x) \xi \cdot \xi \geq 0$ for any $\xi \in \mathbb{R}^{N}$.) With this assumption the operator $L$ is weakly elliptic see Definition 1.1 below. Since $A$ is symmetric and positive semidefinite, there exists a matrix $\mu$ such that $A=\mu^{T} \mu$. Let $l$ be the rank of $\mu$. Since $A$ may be singular, in general we shall have $l \leq N$. Therefore, setting $\nabla_{L}:=\mu \nabla$ and $\operatorname{div}_{L}(\cdot):=\operatorname{div}\left(\mu^{T} \cdot\right)$, the operator $L$ can be rewritten as $L u=\operatorname{div}_{L}\left(\nabla_{L} u\right)$ (formally as the Laplace operator). Finally, even if the entries of the matrix $A$ are smooth, in general then nothing can be said on the regularity of the entries of $\mu$.

Since we are interested in weak solutions of the problems under consideration, we shall allow that the entries of the matrix $\mu$ are singular. However, for simplicity we shall assume that $\mu_{i j}$ are continuous.

Let $\delta:=\left(\delta_{1}, \ldots, \delta_{N}\right)$ be an $N$-uple of positive real numbers. Let $R>0$, we shall denote by $\delta_{R}$ the anisotropic dilation $\delta_{R}: \mathbb{R}^{N} \rightarrow \mathbb{R}^{N}$ defined by

$$
\begin{equation*}
\delta_{R}(x)=\delta_{R}\left(x_{1}, \ldots, x_{N}\right):=\left(R^{\delta_{1}} x_{1}, \ldots, R^{\delta_{N}} x_{N}\right) . \tag{5}
\end{equation*}
$$

The Jacobian of the transformation $\delta_{R}$ is given by $J\left(\delta_{R}\right)=R^{Q}$, where $Q:=\delta_{1}+\delta_{2}+\cdots+$ $\delta_{N}$.

The Jacobian of the transformation $\delta_{R}$ is given by $J\left(\delta_{R}\right)=R^{Q}$, where $Q:=\delta_{1}+\delta_{2}+\cdots+$ $\delta_{N}$.

In Chapter III we shall require that $\nabla_{L}$ is pseudo homogeneous of degree 1 with respect to dilation $\delta_{R}$, that there exist $\delta_{i}>0(i=1 . . N)$ such that

$$
\begin{equation*}
\text { for each } \phi \in \mathscr{C}^{1}\left(\mathbb{R}^{N}\right) \text { and } R>0: \quad \nabla_{L}\left(\phi\left(\delta_{R}(\cdot)\right)\right)=R\left(\nabla_{L} \phi\right)\left(\delta_{R}\right)(\cdot) . \tag{6}
\end{equation*}
$$

A nonnegative continuous function $S: \mathbb{R}^{N} \rightarrow \mathbb{R}_{+}$is called a homogeneous norm, if
i) $S(x)=0$ if and only if $x=0$, and
ii) it is homogeneous of degree 1 with respect to $\delta_{R}$ (i.e. $S\left(\delta_{R}(x)\right)=R S(x)$ ).

An example of homogeneous norm which is differentiable for $x \neq 0$ is given by

$$
\begin{equation*}
S_{\delta}(x):=\left(\sum_{i=1}^{N}\left(x_{i}^{r}\right)^{\frac{d}{\delta_{i}}}\right)^{\frac{1}{r d}} \tag{7}
\end{equation*}
$$

where $d:=\delta_{1} \delta_{2} \cdots \delta_{N}$ and $r$ is the lowest even integer such that $r \geq \max \left\{\delta_{1} / d, \ldots, \delta_{N} / d\right\}$.
Notice that if $S$ is a homogeneous norm differentiable a.e. and $\nabla_{L}$ is pseudo homogeneous of degree 1 with respect to $\delta_{R}$, then $\left|\nabla_{L} S\right|$ is homogeneous of degree 0 with respect to $\delta_{R}$. Hence the function $\left|\nabla_{L} S\right|$ is bounded.

In Chapter III we shall fix a homogeneous norm $S$ differentiable away from 0 and we shall set

$$
\begin{equation*}
\psi:=\left|\nabla_{L} S(\cdot)\right| \tag{8}
\end{equation*}
$$

We define $B_{R}$ the ball of radius $R>0$ generated by the norm $S$, i.e. $B_{R}:=\{x$ : $S(x)<R\}$ and $A_{R}$ stands for the annulus $B_{2 R} \backslash \overline{B_{R}}$. Therefore we have

$$
\left|B_{R}\right|=\int_{B_{R}} d x=R^{Q} \int_{S(x)<1} d x=c_{S} R^{Q} \quad \text { and } \quad\left|A_{R}\right|=c_{S}\left(2^{Q}-1\right) R^{Q} .
$$

A canonical framework for which our results apply, see next chapters, is the Euclidean space $\left(\mathbb{R}^{N},|\cdot|\right)$ with $|\cdot|$ the Euclidean norm. In this case $\mu=I_{N}$ the identity matrix in $N$ dimension, $\nabla_{L}=\nabla$ is the isotropic gradient and $\operatorname{div}_{L}$ is the divergence operator. The dilation $\delta_{R}$ defined by

$$
\delta_{R}(x)=\delta_{R}\left(x_{1}, \ldots, x_{N}\right):=\left(R x_{1}, \ldots, R x_{N}\right)
$$

is isotropic. Here, $Q=N$ is the dimension of the space. In this case, $\psi \equiv 1$ and $B_{R}$ is the Euclidean open ball of radius $R$ centered at the origin.

Another setting in which our results apply is the framework of Carnot Groups. For more details see Appendix A. Further examples will be discussed in Appendix B below.

In what follows $\mathscr{A}: \mathbb{R}^{N} \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$ shall be assumed to be a Caratheodory function, that is for each $t \in \mathbb{R}$ and $\xi \in \mathbb{R}^{l}$ the function $\mathscr{A}(\cdot, t, \xi)$ is measurable; and for a.e. $x \in \mathbb{R}^{N}$, $\mathscr{A}(x, \cdot, \cdot)$ is continuous.

We consider operators $L$ "generated" by $\mathscr{A}$, that is

$$
L(u)(x)=\operatorname{div}_{L}\left(\mathscr{A}\left(x, u(x), \nabla_{L} u(x)\right)\right) .
$$

Our model cases are the p-Laplacian operator, the mean curvature operator and some related generalizations. See Examples 1.3 below.

Definition 1.1 Let $\mathscr{A}: \mathbb{R}^{N} \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$ be a Caratheodory function. The function $\mathscr{A}$ is called weakly elliptic if it generates a weakly elliptic operator $L$ i.e.

$$
\begin{gather*}
\mathscr{A}(x, t, \xi) \cdot \xi \geq 0 \text { for each } x \in \mathbb{R}^{N}, t \in \mathbb{R}, \xi \in \mathbb{R}^{l},  \tag{WE}\\
\mathscr{A}(x, 0, \xi)=0 \quad \text { or } \mathscr{A}(x, t, 0)=0
\end{gather*}
$$

Definition 1.2 Let $\Omega \subset \mathbb{R}^{N}$ be an open set and let $f: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}$ be a Caratheodory function. Let $p \geq 1$. We say that $u \in W_{l o c}^{1, p}(\Omega)$ is a weak solution of

$$
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq f\left(x, u, \nabla_{L} u\right) \quad \text { on } \Omega,
$$

if $\mathscr{A}(\cdot, u, \nabla u) \in L_{l o c}^{p^{\prime}}(\Omega), f\left(\cdot, u, \nabla_{L} u\right) \in L_{\text {loc }}^{1}(\Omega)$, and for any nonnegative $\phi \in \mathscr{C}_{0}^{1}(\Omega)$ we have

$$
-\int_{\Omega} \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} \phi \geq \int_{\Omega} f\left(x, u, \nabla_{L} u\right) \phi .
$$

Definition 2.1 Let $\mathscr{A}: \mathbb{R}^{N} \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$ be a Caratheodory function. The function $\mathscr{A}$ is called weakly elliptic if it generates a weakly elliptic operator $L$ i.e.

$$
\begin{gather*}
\mathscr{A}(x, t, w) \cdot w \geq 0 \text { for each } x \in \mathbb{R}^{N}, t \in \mathbb{R}, w \in \mathbb{R}^{l},  \tag{WE}\\
\mathscr{A}(x, 0, w)=0 \text { or } \mathscr{A}(x, t, 0)=0
\end{gather*}
$$

Let $p>1$, the function $\mathscr{A}$ is called ( $\mathbf{W}-p-\mathbf{C}$ ) (weakly-p-coercive) if it generates a weakly-p-coercive operator $L$ i.e. if there exists a constant $a>0$ such that

$$
\begin{equation*}
(\mathscr{A}(x, t, w) \cdot w) \geq a|\mathscr{A}(x, t, w)|^{p^{\prime}} \text { for each } x \in \mathbb{R}^{N}, t \in \mathbb{R}, w \in \mathbb{R}^{l} \tag{W-p-C}
\end{equation*}
$$

## Example 2.2

1. Let $p>1$. The $p$-Laplacian operator defined on suitable functions $u$ by,

$$
\Delta_{p, L} u=\operatorname{div}_{L}\left(\left|\nabla_{L} u\right|^{p-2} \nabla_{L} u\right)
$$

is an operator generated by $\mathscr{A}(x, t, w):=|w|^{p-2} w$ which is $\mathbf{W}-p-\mathbf{C}$ and $\mathbf{S}-p-\mathbf{C}$.
2. If $\mathscr{A}$ is $\mathbf{S}-p-\mathbf{C}$, then $\mathscr{A}$ is $\mathbf{W}-p-\mathbf{C}$.
3. The mean curvature operator in non parametric form

$$
T(u):=\operatorname{div}_{L}\left(\frac{\nabla_{L} u}{\sqrt{1+\left|\nabla_{L} u\right|^{2}}}\right),
$$

is generated by $\mathscr{A}(x, t, w):=\frac{w}{\sqrt{1+|w|^{2}}}$. In this case $\mathscr{A}$ is $\mathbf{W}-2-\mathbf{C}$ and of mean curva-

Let $p \geq 1$, the function $\mathscr{A}$ is called $\mathbf{W}$-p-C (weakly-p-coercive) (see [4]), if $\mathscr{A}$ is (WE) and it generates a weakly-p-coercive operator $L$, i.e. if there exists a constant $k_{2}>0$ such that

$$
\begin{equation*}
(\mathscr{A}(x, t, \xi) \cdot \xi)^{p-1} \geq k_{2}|\mathscr{A}(x, t, \xi)|^{p} \text { for each } x \in \mathbb{R}^{N}, t \in \mathbb{R}, \xi \in \mathbb{R}^{l} \tag{W-p-C}
\end{equation*}
$$

Let $p>1$, the function $\mathscr{A}$ is called $\mathbf{S}-p-\mathbf{C}$ (strongly-p-coercive) (see [40, 4, 32]), if there exist $k_{1}, k_{2}>0$ constants such that

$$
\begin{equation*}
(\mathscr{A}(x, t, \xi) \cdot \xi) \geq k_{1}|\xi|^{p} \geq k_{2}|\mathscr{A}(x, t, \xi)|^{p^{\prime}} \text { for each } x \in \mathbb{R}^{N}, t \in \mathbb{R}, \xi \in \mathbb{R}^{l} \tag{S-p-C}
\end{equation*}
$$

Examples 1.3 1. Let $p>1$. The p-Laplacian operator defined on suitable functions $u$ by,

$$
\Delta_{p, L} u=\operatorname{div}_{L}\left(\left|\nabla_{L} u\right|^{p-2} \nabla_{L} u\right)
$$

is an operator generated by $\mathscr{A}(x, t, \xi):=|\xi|^{p-2} \xi$ which is $\mathbf{S}-p-\mathbf{C}$.
2. If $\mathscr{A}$ is of mean curvature type, that is $\mathscr{A}$ can be written as $\mathscr{A}(x, t, \xi):=A(|\xi|) \xi$ with $A: \mathbb{R} \rightarrow \mathbb{R}$ a positive bounded continuous function (see [31, 4]), then $\mathscr{A}$ is $\mathbf{W}-2-\mathbf{C}$.
3. The mean curvature operator in non parametric form

$$
T u:=\operatorname{div}_{L}\left(\frac{\nabla_{L} u}{\sqrt{1+\left|\nabla_{L} u\right|^{2}}}\right)
$$

is generated by $\mathscr{A}(x, t, \xi):=\frac{\xi}{\sqrt{1+|\xi|^{2}}}$. In this case $\mathscr{A}$ is $\mathbf{W}-p-\mathbf{C}$ with $1 \leq p \leq 2$ and of mean curvature type but it is not $\mathbf{S}-2-\mathbf{C}$.
4. Let $m>1$. The operator

$$
T_{m} u:=\operatorname{div}\left(\frac{|\nabla u|^{m-2} \nabla u}{\sqrt{1+|\nabla u|^{m}}}\right)
$$

is $\mathbf{W}-p-\mathbf{C}$ for $m \geq p \geq m / 2$.
5. Let $p>1$ and define

$$
L u:=\sum_{i=1}^{N} \partial_{i}\left(\left|\partial_{i} u\right|^{p-2} \partial_{i} u\right)
$$

The operator $L$ is $\mathbf{S}-p-\mathbf{C}$.
6. The operator defined by

$$
\operatorname{div}\left(\frac{|u| \nabla u}{|u|+|\nabla u|}\right)
$$

is $\mathbf{W}-2-\mathrm{C}$.
7. Let $\nu>0$ and define

$$
B_{\nu} u:=\nu \operatorname{div}\left(\frac{|u| \nabla u}{\sqrt{u^{2}+\frac{\nu^{2}}{c^{2}}|\nabla u|^{2}}}\right)
$$

The operator $B_{\nu}$ is related to the so called "tempered diffusion equation" or "relativistic heat equation" (here $\nu$ is a constant representing a kinematic viscosity and c the speed of light). See [5] and [39]. This operator is W-2-C.
8. Letting $\nu \rightarrow+\infty$ in $B_{\nu}$ above, we obtain the operator that appears in the so called "diffusion equation in transparent media",

$$
B_{\infty} u:=c \operatorname{div}\left(\frac{|u| \nabla u}{|\nabla u|}\right)
$$

See [5]. This operator is obviously (WE).

## 3 Quasilinear weakly elliptic operators

In this section we consider a class of quasilinear elliptic operators for which we can prove a suitable version of inequality (9). We point out that the following results hold for a wide class of differential operators for which no group invariance is required. Of course the price to pay for this generality is that we need to consider solutions that belong to the space $W_{l o c}^{1, p}(\Omega)$. Under additional assumption on the underline group structure and suitable invariance, it is possible to handle solutions that belong to the more natural space $W_{L, l o c}^{1, p}(\Omega)$. See Remark 3.5 for the exact meaning.

Let $\Omega$ be an open set contained in $\mathbb{R}^{N}, p \geq 1$ and $u \in W_{\text {loc }}^{1, p}(\Omega)$.
Theorem 3.1 (Kato's inequality: The quasilinear case) Let $\mathscr{A}$ be such that

$$
\begin{equation*}
\mathscr{A}(x, t, \xi) \cdot \xi \geq 0 \quad \text { for any } x \in \Omega, t \in \mathbb{R}, \xi \in \mathbb{R}^{l} \tag{14}
\end{equation*}
$$

Let $f \in L_{\text {loc }}^{1}(\Omega)$ and let $u \in W_{\text {loc }}^{1, p}(\Omega)$ be a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq f \quad \text { on } \Omega \tag{15}
\end{equation*}
$$

Then

$$
\begin{equation*}
\operatorname{div}_{L}\left(\operatorname{sign}^{+} u \mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq \operatorname{sign}^{+} u f \quad \text { on } \Omega \tag{16}
\end{equation*}
$$

Moreover if

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)=f \quad \text { on } \Omega, \tag{17}
\end{equation*}
$$

then

$$
\begin{equation*}
\operatorname{div}_{L}\left(\operatorname{sign} u \mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq \operatorname{sign} u f \quad \text { on } \Omega . \tag{18}
\end{equation*}
$$

In particular, if $\mathscr{A}$ is $(W E)$, then $u^{+}$is a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u^{+}, \nabla_{L} u^{+}\right)\right) \geq \operatorname{sign}^{+} u f \quad \text { on } \Omega . \tag{19}
\end{equation*}
$$

If in addition $\mathscr{A}$ is odd i.e.

$$
\begin{equation*}
\mathscr{A}(x,-t,-\xi)=-\mathscr{A}(x, t, \xi), \tag{20}
\end{equation*}
$$

and $u$ is a solution of (17), then $|u|$ satisfies,

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x,|u|, \nabla_{L}|u|\right)\right) \geq \operatorname{sign} u f \quad \text { on } \Omega . \tag{21}
\end{equation*}
$$

## The proof of Kato's inequality is based on the following:

Lemma 3.2 Let $\mathscr{A}$ satisfy (14). Let $f \in L_{\text {loc }}^{1}(\Omega)$ and let $u \in W_{\text {loc }}^{1, p}(\Omega)$ be a weak solution of

$$
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq f \quad \text { on } \Omega .
$$

Let $\gamma \in \mathscr{C}^{1}(\mathbb{R})$ be nonnegative and such that $\gamma, \gamma^{\prime}$ are bounded. Then,

$$
\begin{equation*}
\int_{\Omega} f \gamma(u) \phi+\int_{\Omega} \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} u \gamma^{\prime}(u) \phi \leq-\int_{\Omega} \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} \phi \gamma(u) . \tag{22}
\end{equation*}
$$

In particular if $\gamma^{\prime} \geq 0$, we have

$$
\begin{equation*}
\operatorname{div}_{L}\left(\gamma(u) \mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq \gamma(u) f \quad \text { on } \Omega . \tag{23}
\end{equation*}
$$

Moreover if

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)=f \quad \text { on } \Omega, \tag{24}
\end{equation*}
$$

then (23) holds provided $\gamma^{\prime} \geq 0$ regardless the nonnegativity assumption on $\gamma$.

Proof of Theorem 3.1. In order to prove (16) it suffices to approximate sign ${ }^{+}$with a family of nonnegative smooth bounded functions which are nondecreasing and with bounded derivative.

To this end we introduce,

$$
\gamma_{\epsilon}(t):= \begin{cases}\left(\frac{2}{\pi} \arctan (t / \epsilon)\right)^{2}, & \text { if } t \geq 0 \\ 0 & \text { if } t<0\end{cases}
$$

Then $0 \leq \gamma_{\epsilon}<1$ and $\gamma_{\epsilon}(t) \rightarrow \operatorname{sign}^{+}(t)$. Applying Lemma 3.2, from (23) with $\gamma$ replaced by $\gamma_{\epsilon}$ we obtain,

$$
\begin{equation*}
\int_{\Omega} f \gamma_{\epsilon}(u) \phi \leq-\int_{\Omega} \gamma_{\epsilon}(u) \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} \phi \tag{27}
\end{equation*}
$$

Passing to the limit $\epsilon \rightarrow 0$ in (27), by Lebesgue dominated convergence theorem we finally obtain (16), i.e.

$$
\begin{equation*}
\int_{\Omega} \operatorname{sign}^{+}(u) f \phi \leq-\int_{\Omega} \operatorname{sign}^{+}(u) \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} \phi \tag{28}
\end{equation*}
$$

In addition, if $\mathscr{A}$ is (WE) from the identity

$$
\operatorname{sign}^{+}(u) \mathscr{A}\left(x, u, \nabla_{L} u\right)=\mathscr{A}\left(x, u^{+}, \nabla_{L} u^{+}\right) \text {on } \Omega,
$$

inequality (19) follows.
The proof of (18) follows once again by applying the above argument to the family of functions

$$
\gamma_{\epsilon}(t):=\frac{2}{\pi} \arctan (t / \epsilon) .
$$

## 4 Examples

Inequality (19) holds for all (WE) operators, in particular for all operators listed in Examples 1.3. In this section we illustrate in detail some classes of operators for which Kato's inequality holds.

## $4.1 \quad p$-Laplacian type operators

Let $f \in L_{l o c}^{1}(\Omega)$ and let $u \in W_{l o c}^{1, p}(\Omega)$ be a solution of the inequality,

$$
L_{p} u:=\operatorname{div}_{L}\left(\left|\nabla_{L} u\right|^{p-2} \nabla_{L} u\right) \geq f \quad \text { on } \Omega .
$$

Then,

$$
L_{p} u^{+} \geq \operatorname{sign}^{+}(u) f \quad \text { on } \Omega
$$

In particular if $\nabla_{L}$ is the Euclidean gradient $\nabla$ and $u \in W_{l o c}^{1, p}(\Omega)$ is a weak solution of

$$
\Delta_{p} u \geq f \quad \text { on } \Omega
$$

then $u^{+} \in W_{l o c}^{1, p}(\Omega)$ is a weak solution of

$$
\begin{equation*}
\Delta_{p} u^{+} \geq \operatorname{sign}^{+}(u) f \quad \text { on } \Omega \tag{34}
\end{equation*}
$$

As a consequence of (34), we have the following. See [41, 17] for a different proof under stronger assumption on the solutions.

Proposition 4.1 Let $q>p-1>0$. If $u \in W_{\text {loc }}^{1, p}\left(\mathbb{R}^{N}\right) \cap L_{\text {loc }}^{q}\left(\mathbb{R}^{N}\right)$ is a weak solution of

$$
\begin{equation*}
\Delta_{p} u \geq|u|^{q-1} u \quad \text { on } \mathbb{R}^{N}, \tag{35}
\end{equation*}
$$

then $u \leq 0$ a.e. on $\mathbb{R}^{N}$. In particular, if in (35) the equality sign holds, then $u \equiv 0$ a.e. on $\mathbb{R}^{N}$.

Proof. Let $q>p-1$ and set

$$
u_{R}(x):=\frac{c R^{\beta}}{\left(R^{p /(p-1)}-|x|^{p /(p-1)}\right)^{\alpha}} \quad x \in B_{R},
$$

with

$$
\alpha:=\frac{p}{q-p+1}, \quad \beta:= \begin{cases}0 & \text { if } q \leq 1, \\ \frac{\alpha p}{p-1}-\frac{p}{q-1} & \text { if } q>1,\end{cases}
$$

and the positive constant $c$ satisfies $c^{q-p+1}=\left(\frac{\alpha p}{p-1}\right)^{p-1} \max \{N, p(\alpha+1)\}$.
The function $u_{R}$ is a slight modification of the Loewner-Nirenberg [27] function used by Brezis in his original argument [6] for $p=2$. It is easy to check that for $R>0, u_{R}$ is a solution of the inequality

$$
-\Delta_{p} u_{R}+u_{R}^{q} \geq 0 \quad \text { on } B_{R}
$$

Indeed

$$
\frac{\Delta_{p} u_{1}}{u_{1}^{q}}=\left(\frac{\alpha p}{p-1}\right)^{p-1} c^{-q+p-1}\left[N+(p \alpha+p-N) r^{p /(p-1)}\right] \leq 1 .
$$

Now, since

$$
u_{R}=\frac{c R^{\beta-\alpha p /(p-1)}}{\left(1-\left(\frac{|x|}{R}\right)^{p /(p-1)}\right)^{\alpha}}=R^{\beta-\alpha p /(p-1)} u_{1}\left(\frac{|x|}{R}\right)
$$

for $R \geq 1$ we have

$$
\frac{\Delta_{p} u_{R}}{u_{R}^{q}}=\frac{R^{\beta-\alpha p /(p-1)} R^{-p}\left(\Delta_{p} u_{1}\right)(|x| / R)}{R^{q(\beta-\alpha p /(p-1))} u_{1}^{q}(|x| / R)} \leq R^{(1-q)(\beta-\alpha p /(p-1))-p} \leq 1
$$

Let $u \in W_{l o c}^{1, p}\left(\mathbb{R}^{N}\right) \cap L_{l o c}^{q}\left(\mathbb{R}^{N}\right)$ be a weak solution of (35).
Applying inequality (34) it follows that, in the weak sense we have,

$$
\Delta_{p} u^{+} \geq\left(u^{+}\right)^{q} \quad \text { on } \quad \mathbb{R}^{N}
$$

Since $u^{+}$is $p$-subharmonic, from [29] we deduce $u^{+} \in L_{l o c}^{\infty}\left(\mathbb{R}^{N}\right)$. By the weak comparison principle we deduce that, for any $R>1$ we have $u^{+} \leq u_{R}$ a.e. on $B_{R}$. Since $u_{R} \rightarrow 0$ for $R \rightarrow+\infty$, it follows that $u^{+} \leq 0$ a.e. on $\mathbb{R}^{N}$. This completes the proof.

## The reduction principles

Throughout the following sections, unless otherwise stated, $\Omega$ stands for an open subset contained in $\mathbb{R}^{N}$ and $\mathscr{A}$ is (WE).

## 5 The role of positive solutions

In this section we are going to develop the main ideas that we shall use throughout this paper when studying quasilinear elliptic inequalities of coercive type. It is known [16], that dealing with non coercive problems of the form,

$$
\begin{equation*}
-\operatorname{div}_{L}\left(\mathscr{A}\left(x, v, \nabla_{L} v\right)\right) \geq f(x, v), \quad v \geq 0, \quad \text { on } \mathbb{R}^{N} \tag{36}
\end{equation*}
$$

where $f: \mathbb{R}^{N} \times \mathbb{R} \rightarrow \mathbb{R}$ is a nonnegative function, the existence or nonexistence of positive solutions in a suitable functional space is determined only by the behavior of the non linearity $f$ near zero. On the other hand in the coercive case, that is

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, v, \nabla_{L} v\right)\right) \geq g(x, v) \quad \text { on } \mathbb{R}^{N} \tag{37}
\end{equation*}
$$

and $g: \mathbb{R}^{N} \times \mathbb{R} \rightarrow \mathbb{R}$ is a given function, a first step for the understanding the solutions set, is to reduce our problem to an inequality with solutions having a definite sign. A remarkable fact is that this reduction is always possible for weakly elliptic quasilinear inequalities. Even though, as we shall see during the course, this reduction leads to nontrivial problems in finding good a priori estimates on the possible nonnegative solutions of (37).

In keeping with the notation and terminology introduced above, we have.

Theorem 5.1 Let $f: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}$ be a Caratheodory function satisfying

$$
\begin{equation*}
f(x, 0, \xi)=0 \quad \text { or } \quad f(x, t, 0)=0 \tag{38}
\end{equation*}
$$

Let $p \geq 1$ and let $X \subset W_{l o c}^{1, p}(\Omega)$ be a set such that if $u \in X$ then $u^{+} \in X$. Assume that the problem

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, v, \nabla_{L} v\right)\right) \geq f\left(x, v, \nabla_{L} v\right) \quad v \geq 0 \quad \text { on } \Omega, \tag{39}
\end{equation*}
$$

has no nontrivial weak solutions in $X$.
Then any weak solution of the problem

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq f\left(x, u, \nabla_{L} u\right) \quad u \in X, \tag{40}
\end{equation*}
$$

is nonpositive, i.e.

$$
u(x) \leq 0 \quad \text { a.e. } \quad x \in \Omega .
$$

Proof. Let $u \in X$ be a solution of (40). By inequality (19) and by hypothesis (38) it follows that

$$
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u^{+}, \nabla_{L} u^{+}\right)\right) \geq \operatorname{sign}^{+} u f\left(x, u, \nabla_{L} u\right)=f\left(x, u^{+}, \nabla_{L} u^{+}\right) \quad \text { on } \Omega .
$$

Hence $u^{+} \in X$ is a nonnegative solution of (39). Thus $u^{+} \equiv 0$ a.e. on $\Omega$. This completes the proof.

In what follows for a given function $\mathscr{A}: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$, we shall denote with $\overline{\mathscr{A}}$ the function $\overline{\mathscr{A}}: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}^{l}$ defined by

$$
\begin{equation*}
\overline{\mathscr{A}}(x, t, \xi):=-\mathscr{A}(x,-t,-\xi) . \tag{41}
\end{equation*}
$$

Notice that if $\mathscr{A}$ is weakly elliptic or $\mathbf{W}-p-\mathbf{C}$ or $\mathbf{S}-p-\mathbf{C}$ then $\overline{\mathscr{A}}$ has the same properties. Moreover if $\mathscr{A}$ is odd (see (20)), then $\overline{\mathscr{A}}=\mathscr{A}$.

An immediate implication of the above theorems is the following obvious consequence for non coercive problems.

Theorem 5.3 Let $f: \Omega \times \mathbb{R} \times \mathbb{R}^{l} \rightarrow \mathbb{R}$ be a Caratheodory function satisfying (38). Let $p \geq 1$ and let $X \subset W_{\text {loc }}^{1, p}(\Omega)$ be a set such that if $u \in X$ then $-u, u^{+} \in X$. Assume that the problem

$$
\begin{equation*}
\operatorname{div}_{L}\left(\overline{\mathscr{A}}\left(x, v, \nabla_{L} v\right)\right) \geq f\left(x,-v,-\nabla_{L} v\right) \quad v \geq 0 \quad \text { on } \Omega, \tag{42}
\end{equation*}
$$

has no nontrivial weak solutions in $X$.
Then any weak solution of the problem

$$
\begin{equation*}
-\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq f\left(x, u, \nabla_{L} u\right) \quad \text { on } \Omega, \quad u \in X \tag{43}
\end{equation*}
$$

is nonnegative, i.e.

$$
u(x) \geq 0 \quad \text { a.e. } \quad x \in \Omega
$$

Proof. Let $u \in X$ be a solution of (43). The function $w:=-u \in X$ is a solution of

$$
\operatorname{div}_{L}\left(\overline{\mathscr{A}}\left(x, v, \nabla_{L} v\right)\right) \geq f\left(x,-v,-\nabla_{L} v\right) \quad \text { on } \Omega, \quad v \in X .
$$

Since $\overline{\mathscr{A}}$ is weakly elliptic and $f$ satisfies (38) we are in the position to apply Theorem 5.1 , which yields $w \leq 0$ on $\Omega$. This completes the proof.

Theorem 5.4 Let $f: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be a Caratheodory function satisfying (38) and set

$$
\bar{f}(x, t, \xi)=-f(x,-t,-\xi) .
$$

Let $p \geq 1$ and let $X \subset W_{\text {loc }}^{1, p}(\Omega)$ be a set such that if $u \in X$ then $-u, u^{+} \in X$. Assume that the problems,

$$
\begin{align*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, v, \nabla_{L} v\right)\right) \geq f\left(x, v, \nabla_{L} v\right), & v \geq 0, \quad \text { on } \Omega,  \tag{44}\\
\operatorname{div}_{L}\left(\overline{\mathscr{A}}\left(x, v, \nabla_{L} v\right)\right) \geq \bar{f}\left(x, v, \nabla_{L} v\right), & v \geq 0, \quad \text { on } \Omega, \tag{45}
\end{align*}
$$

have no nontrivial weak solutions in $X$.
Then the problem

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)=f\left(x, u, \nabla_{L} u\right) \quad \text { on } \Omega \quad u \in X, \tag{46}
\end{equation*}
$$

has no nontrivial weak solutions.

Proof. Let $u \in X$ be a solution of (43). The function $w:=-u \in X$ is a solution of

$$
\operatorname{div}_{L}\left(\overline{\mathscr{A}}\left(x, v, \nabla_{L} v\right)\right) \geq f\left(x,-v,-\nabla_{L} v\right) \quad \text { on } \quad \Omega, \quad v \in X .
$$

Since $\overline{\mathscr{A}}$ is weakly elliptic and $f$ satisfies (38) we are in the position to apply Theorem 5.1 , which yields $w \leq 0$ on $\Omega$. This completes the proof.

Theorem 5.4 Let $f: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be a Caratheodory function satisfying (38) and set

$$
\bar{f}(x, t, \xi)=-f(x,-t,-\xi) .
$$

Let $p \geq 1$ and let $X \subset W_{\text {loc }}^{1, p}(\Omega)$ be a set such that if $u \in X$ then $-u, u^{+} \in X$. Assume that the problems,

$$
\begin{align*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, v, \nabla_{L} v\right)\right) \geq f\left(x, v, \nabla_{L} v\right), & v \geq 0, \quad \text { on } \Omega,  \tag{44}\\
\operatorname{div}_{L}\left(\overline{\mathscr{A}}\left(x, v, \nabla_{L} v\right)\right) \geq \bar{f}\left(x, v, \nabla_{L} v\right), & v \geq 0, \quad \text { on } \Omega, \tag{45}
\end{align*}
$$

have no nontrivial weak solutions in $X$.
Then the problem

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)=f\left(x, u, \nabla_{L} u\right) \quad \text { on } \Omega \quad u \in X, \tag{46}
\end{equation*}
$$

has no nontrivial weak solutions.

### 5.1 Applications: maximum and comparison principles

Although it is not exactly the direction in which we have been going, it seems appropriate to include here some interesting examples and applications of the reduction ideas.

Let $\Omega \subset \mathbb{R}^{N}$ be an open set and let $u, v \in L_{l o c}^{1}(\Omega)$. In what follows the inequality $u \leq v$ in $\partial \Omega$ should be understood in the sense that for every $\epsilon>0$ there exists a neighborhood $V$ of $\partial \Omega$ such that for a.e. $x \in V$ we have $u(x) \leq v(x)+\epsilon$.

Moreover we shall need of the following hypothesis on $\nabla_{L}$.

$$
\begin{equation*}
\text { If } O \subset \mathbb{R}^{N} \text { is an open connected set and } \nabla_{L} u \equiv 0 \Rightarrow u \equiv \text { const on } O \tag{47}
\end{equation*}
$$

This assumption obviously holds if $\nabla_{L}=\nabla$, the standard Euclidean gradient. It also holds in Carnot group setting as well as in all the examples of Appendix B except for the gradient of $l$ variables, see Example B.1. A general condition assuring the validity of (47) is related to the Hörmander condition and to Caratheodory-Chow-Rashevsky theorem, see [8].

Theorem 5.7 (The weak maximum principle) Let $\mathscr{A}$ be weakly elliptic such that for a.e. $x \in \Omega$,

$$
\begin{equation*}
\text { if } \mathscr{A}(x, t, \xi)=0 \quad \text { then } \quad t=0 \text { or } \xi=0 \tag{48}
\end{equation*}
$$

Assume that (47) holds.
Let $p \geq 1$ and let $u \in W_{\text {loc }}^{1, p}(\Omega)$ be a weak solution of

$$
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq 0 \quad \text { on } \Omega
$$

Suppose that $\Omega^{\prime} \subset \subset \Omega$ and $u \leq 0$ on $\partial \Omega^{\prime}$. Then $u \leq 0$ a.e. on $\Omega^{\prime}$.
Theorem 5.8 (The weak comparison principle) Let $\Omega \subset \mathbb{R}^{N}$ be a bounded open set. Let $\mathscr{A}$ be a monotone function. Let $f, g: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be Caratheodory functions such that

$$
\begin{equation*}
f(x, t) \geq g(x, t), \quad \text { a.e. } x \in \Omega, \quad t \in \mathbb{R} \tag{50}
\end{equation*}
$$

and at least one of them is nondecreasing with respect to $t$ variable. Assume that (47) holds and one of the following conditions

1. $\mathscr{A}$ is strictly monotone;
2. $f(x, t)$ or $g(x, t)$ is increasing with respect to $t$ variable;
is satisfied.
Let $u, v \in W_{\text {loc }}^{1, p}(\Omega)$ be such that

$$
\begin{equation*}
-\operatorname{div}_{L}\left(\mathscr{A}\left(x, v, \nabla_{L} v\right)\right)+g(x, v) \geq-\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+f(x, u) \tag{51}
\end{equation*}
$$

If $u \leq v$ on $\partial \Omega$, then $u \leq v$ a.e. in $\Omega$.

Theorem 5.9 (A generalized weak maximum principle) Let $\Omega \subset \mathbb{R}^{N}$ be a bounded open set and (47) holds. Suppose that there exists a Caratheodory function $G: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ and a constant $\bar{\lambda}>0$ such that for any nonnegative $v \in W_{0}^{1, p}(\Omega)$ we have $G(\cdot, v(\cdot)) \in$ $L^{1}(\Omega)$ and

$$
\begin{equation*}
\int_{\Omega} \mathscr{A}\left(x, v, \nabla_{L} v\right) \cdot \nabla_{L} v \geq \bar{\lambda} \int_{\Omega} G(x, v) \quad \text { for any } v \geq 0, v \in W_{0}^{1, p}(\Omega) . \tag{54}
\end{equation*}
$$

Assume that either (48) holds or

$$
\begin{equation*}
\text { if } v \in W_{0}^{1, p}(\Omega), v \geq 0, v \not \equiv 0 \Rightarrow \int_{\Omega} G(x, v)>0 \tag{55}
\end{equation*}
$$

Let $g: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be a Caratheodory function such that $g(x, 0)=0$, and there exists $c_{g}>0$ such that $0 \leq g(x, t) t \leq c_{g} G(x, t)$ for $t>0$. Let $u \in W^{1, p}(\Omega)$ be a weak solution of

$$
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+\lambda g(x, u) \geq 0, \quad \text { on } \Omega, \quad u \leq 0 \text { on } \partial \Omega
$$

i) If $\lambda<c_{g} / \bar{\lambda}$, then $u \leq 0$ a.e. on $\Omega$.
ii) If $\lambda=c_{g} / \bar{\lambda}$ and the constant $\bar{\lambda}$ in (54) is not achieved in $W_{0}^{1, p}(\Omega)$, then $u \leq 0$ a.e. on $\Omega$.

The following Hardy inequality will play an important role in what follows (see [12] for the proof and several other results).

Theorem 5.11 Let $p>1$. Let $d: \Omega \rightarrow \mathbb{R}$ be a nonnegative non constant measurable function and $\alpha \in \mathbb{R}, \alpha \neq 0$ such that

$$
d^{-p}\left|\nabla_{L} d\right|^{p}, d^{(\alpha-1)(p-1)}\left|\nabla_{L} d\right|^{p-1} \in L_{l o c}^{1}(\Omega) .
$$

If $-L_{p}\left(d^{\alpha}\right) \geq 0$ in the weak sense, then for every $u \in \mathscr{C}_{0}^{1}(\Omega)$ we have

$$
\begin{equation*}
\left(\frac{|\alpha|(p-1)}{p}\right)^{p} \int_{\Omega} \frac{|u|^{p}}{d^{p}}\left|\nabla_{L} d\right|^{p} d x \leq \int_{\Omega}\left|\nabla_{L} u\right|^{p} d x . \tag{57}
\end{equation*}
$$

In particular:

1. If $\nabla_{L}$ is the horizontal gradient on a Carnot group $\mathbb{G}$ and $S$ is a homogeneous norm such that $L_{p} S^{\frac{p-Q}{p-1}}=c \delta_{0}{ }^{3}$ on $\mathbb{G}$ with $Q>p>1$, then

$$
\begin{equation*}
\left(\frac{Q-p}{p}\right)^{p} \int_{\mathbb{G}} \frac{|u|^{p}}{S^{p}}\left|\nabla_{L} S\right|^{p} d x \leq \int_{\mathbb{G}}\left|\nabla_{L} u\right|^{p} d x, \quad u \in D_{L}^{1, p}(\mathbb{G})^{4} \tag{58}
\end{equation*}
$$

where the constant $\left(\frac{Q-p}{p}\right)^{p}$ is sharp and it is not achieved.
2. If the first column of the matrix $\mu$ is such that $\mu_{11}=1$ and $\mu_{k 1}=0$ for $k=2 . . l^{5}$ and $\Omega$ is bounded in the $x_{1}$ direction, then there exists $c>0$ such that

$$
\begin{equation*}
c^{p} \int_{\Omega}|u|^{p} \leq \int_{\Omega}\left|\nabla_{L} u\right|^{p}, \quad u \in \mathscr{C}_{0}^{1}(\Omega) . \tag{59}
\end{equation*}
$$

Some direct consequences of Theorem (5.9) are the following.
Theorem 5.12 Let $\nabla_{L}$ be the horizontal gradient on a Carnot group $\mathbb{G}$. Let $Q>p>1$ and let $S$ be a homogeneous norm such that $L_{p} S^{\frac{p-Q}{p-1}}=c \delta_{0}$ on $\mathbb{G}$.

Let $\Omega \subset \mathbb{G}$ be a bounded open set. Let $u \in W_{L}^{1, p}(\Omega)$ be a weak solution of

$$
L_{p} u+\lambda \frac{\left|\nabla_{L} S\right|^{p}}{S^{p}}|u|^{p-2} u \geq 0 \quad \text { on } \Omega, \quad u \leq 0 \quad \text { on } \partial \Omega,
$$

with $\lambda \leq\left(\frac{Q-p}{p}\right)^{p}$. Then $u \leq 0$ a.e. on $\Omega$.
Another simple application of Theorem (5.9) is the following.
Theorem 5.14 Let $\nabla$ be the Euclidean gradient on $\mathbb{R}^{N}$. Let $\Omega \subset \mathbb{R}^{N}$ be a bounded open set with Lipschitz boundary and $p>1$. Set

$$
\delta(x):=\operatorname{dist}(x, \partial \Omega) \quad x \in \Omega .
$$

Then there exists $\lambda(\Omega, p)>0$ such that if $\lambda<\lambda(\Omega, p)$ and $u \in W^{1, p}(\Omega)$ is a weak solution of

$$
\Delta_{p} u+\lambda \frac{|u|^{p-2} u}{\delta^{p}} \geq 0 \quad \text { on } \Omega, \quad u \leq 0 \quad \text { on } \partial \Omega,
$$

then $u \leq 0$ a.e. on $\Omega$. Moreover, $0<\lambda(\Omega, p) \leq\left(\frac{p-1}{p}\right)^{p}$,
The proof is based on the Hardy inequality

$$
\begin{equation*}
\int_{\Omega}|\nabla u|^{p} \geq \lambda(\Omega, p) \int_{\Omega} \frac{|u|^{p}}{\delta^{p}} \tag{60}
\end{equation*}
$$

It is known that the best constant $\lambda(\Omega, p)$ in (60) is such that $\lambda(\Omega, p) \leq\left(\frac{p-1}{p}\right)^{p}$ and if $\Omega$ is convex then $\lambda(\Omega, p)=\left(\frac{p-1}{p}\right)^{p}$. See [30]. Notice that if $\lambda=\lambda(\Omega, p)$, then the above theorem holds provided $\lambda(\Omega, p)$ is not achieved. For further information on (60) we refer to $[1,30,12,25]$ and the references therein.

## A priori estimates, positivity results and Liouville theorems

In what follows we shall assume that $\mathscr{A}$ is $\mathbf{W}-p-\mathbf{C}$ with $p>1$. Throughout all sections, except Section 10, we shall assume that the vector field $\nabla_{L}$ satisfies (6), that is it homogeneous of degree one with respect to a dilation $\delta_{R}$ as specified in Section 1. However for convenience of the reader we state our assumptions at the beginning of each sections.

## 10 General a priori estimates

Let $\Omega \subset \mathbb{R}^{N}$ be an open set. Let $V \in L_{\text {loc }}^{\infty}(\Omega)$ be nonnegative and let $\mathscr{A}$ be $\mathbf{W}$-p-C with $p>1$. The following preliminary lemmata will play an important role in the proof of our main result (see Theorem 10.5 below).

Lemma 10.1 Let $g \in L_{\text {loc }}^{1}(\Omega)$ be nonnegative and let $u \in W_{l o c}^{1, p}(\Omega)$ be a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+V u^{p-1} \geq g, \quad u \geq 0, \quad \text { on } \Omega \tag{94}
\end{equation*}
$$

Let $s \geq 1$. If $u^{s+p-1} \in L_{\text {loc }}^{1}(\Omega)$, then

$$
\begin{equation*}
g u^{s}, \quad \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} u u^{s-1} \in L_{l o c}^{1}(\Omega) \tag{95}
\end{equation*}
$$

and for any nonnegative $\phi \in \mathscr{C}_{0}^{1}(\Omega)$ we have,

$$
\begin{equation*}
\int_{\Omega} g u^{s} \phi+c_{1} s \int_{\Omega} \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} u u^{s-1} \phi \leq c_{2} s^{1-p} \int_{\Omega} u^{s+p-1} \frac{\left|\nabla_{L} \phi\right|^{p}}{\phi^{p-1}}+\int_{\Omega} V u^{s+p-1} \phi, \tag{96}
\end{equation*}
$$

where $c_{1}=1-\frac{\epsilon^{p^{\prime}}}{p^{\prime} k_{2}}>0, c_{2}=\frac{p^{p}}{p \epsilon^{p}}$ and $\epsilon>0$ is sufficiently small.
Remark 10.2 i) Notice that form the above result it follows that if $u \in W_{l o c}^{1, p}(\Omega)$ is a weak solution of (94), then $g u \in L_{l o c}^{1}(\Omega)$.
ii) The above lemma still holds if we replace the function $g \in L_{l o c}^{1}(\Omega)$ with a regular Borel measure on $\Omega$.

Remark 10.3 i) The above lemma holds for $s>0$. Indeed if $0<s<1$ the proof follows the same arguments as above. To this end in (97) it is enough to choose $\gamma:=\gamma_{n}(u+\delta)$ where $\gamma_{n}$ is defined by (98).
ii) If $V \leq 0$, then the assumption $u^{s+p-1} \in L_{l o c}^{1}(\Omega)$, is not needed for the validity of (95). Indeed what that really matters is $u^{s+p-1} \in L_{l o c}^{1}(S)$ where $S$ is the support of $\nabla_{L} \phi$. This remark will be useful when dealing with inequalities on unbounded set.

Let $a: \Omega \rightarrow \mathbb{R}$ be a nonnegative measurable function. Let $u$ be weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+V u^{p-1} \geq a(x) u^{q}, \quad u \geq 0, \quad \text { on } \Omega . \tag{99}
\end{equation*}
$$

The main strategy to obtain a priori estimates is to use the family of test functions $u^{\alpha} \phi$ where $\alpha>0$ is a suitable constant that will be chosen according to our needs. See [31]. However, a priori it is not clear why, after multiplying the inequality by $u^{\alpha} \phi$, this family is admissible, i.e. why $u^{q+\alpha} \in L_{\text {loc }}^{1}(\Omega)$. A sufficient condition for the admissibility of the family $u^{\alpha} \phi$ is contained in the following.
Lemma 10.4 Let $u$ be a weak solution of (99) with $q>p-1$. Assume that there exists $\bar{\alpha}>1$ such that $a^{-\frac{\bar{\alpha}+p-1}{q-p+1}} \in L_{l o c}^{1}(\Omega)$.

If $1 \leq \alpha<\bar{\alpha}$, then

$$
\begin{equation*}
a u^{q+\alpha}, u^{\alpha+p-1} \in L_{l o c}^{1}(\Omega), \tag{100}
\end{equation*}
$$

and for any nonnegative $\phi \in \mathscr{C}_{0}^{1}(\Omega)$, the following inequalities hold

$$
\begin{equation*}
\int_{\Omega} a u^{q+\alpha} \phi+c_{1} \alpha \int_{\Omega} \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} u u^{\alpha-1} \phi \leq c_{2} \alpha^{1-p} \int_{\Omega} u^{\alpha+p-1} \frac{\left|\nabla_{L} \phi\right|^{p}}{\phi^{p-1}}+\int_{\Omega} V u^{\alpha+p-1} \phi, \tag{101}
\end{equation*}
$$

$$
\begin{align*}
& \int_{\Omega} a u^{q+\alpha} \phi+c_{1} \alpha \int_{\Omega} \mathscr{A}\left(x, u, \nabla_{L} u\right) \cdot \nabla_{L} u u^{\alpha-1} \phi \leq \\
& \quad c_{2} \alpha^{1-p}\left(\int_{S} a u^{q+\alpha} \phi\right)^{1 / \chi}\left(\int_{S} \frac{\left|\nabla_{L} \phi\right|^{p \chi^{\prime}}}{\phi^{p \chi^{\prime}-1}} a^{-\frac{\alpha+p-1}{q-p+1}}\right)^{1 / \chi^{\prime}}+\int_{\Omega} V u^{\alpha+p-1} \phi, \tag{102}
\end{align*}
$$

where $\chi:=\frac{q+\alpha}{\alpha+p-1}, \chi^{\prime}:=\frac{q+\alpha}{q-p+1}$ and $S$ is the support of $\nabla_{L} \phi$.
In particular if

$$
\text { for any } C \subset \subset \Omega: \quad \operatorname{ess} \inf _{C} a>0
$$

then for any $\alpha>0$, we have a $u^{q+\alpha} \in L_{l o c}^{1}(\Omega)$.

Theorem 10.5 Let $u$ be a weak solution of (99) with $q>p-1$ and $V \leq 0$. Assume that there exists $\bar{\alpha}>1$ such that $a^{-\frac{\bar{\alpha}+p-1}{q-p+1}} \in L_{l o c}^{1}(\Omega)$.

Then

$$
a u^{q+\bar{\alpha}}, u^{\bar{\alpha}+p-1} \in L_{l o c}^{1}(\Omega)
$$

and for any $1 \leq \alpha \leq \bar{\alpha}$ and for any nonnegative $\phi \in \mathscr{C}_{0}^{1}(\Omega)$ the inequalities (101), (102) hold and

$$
\begin{equation*}
\int_{\Omega} a u^{q+\alpha} \phi \leq\left(c_{2} \alpha^{1-p}\right)^{\chi^{\prime}} \int_{\Omega} \frac{\left|\nabla_{L} \phi\right|^{p \chi^{\prime}}}{\phi^{p \chi^{\prime}-1}} a^{-\frac{\alpha+p-1}{q-p+1}} \tag{106}
\end{equation*}
$$

where $\chi^{\prime}:=\frac{q+\alpha}{q-p+1}$.

## 11 Universal a priori estimates

In this section $\Omega \subset \mathbb{R}^{N}$ is an open set, $\nabla_{L}$ is the horizontal gradient on a Carnot group $\mathbb{G}$ and $\mathscr{A}$ is $\mathbf{S}-p-\mathbf{C}$ (see Definition 1.1). We shall denote with $|\cdot|_{L}$ a homogeneous norm on $\mathbb{G}$.

Theorem 11.1 Let $q>p-1$ and $c>0$. Assume that $f \in \mathscr{C}(\mathbb{R})$ satisfies $f(t) \geq c t^{q}$ for $t>0$. Then there exists a constant $C=C(f, \mathbb{G}, \mathscr{A})>0$ such that if $u$ is a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+\mathscr{B}\left(x, u, \nabla_{L} u\right) \geq f(u) \quad \text { on } \Omega \tag{108}
\end{equation*}
$$

with $\mathscr{B}(x, t, \xi) \leq 0$ for $t \geq 0$, then

$$
\begin{equation*}
u(x) \leq \operatorname{Cdist}(x, \partial \Omega)^{-\frac{p}{q-p+1}} \quad \text { a.e. } x \in \Omega \tag{109}
\end{equation*}
$$

In particular if $u$ is a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+\mathscr{B}\left(x, u, \nabla_{L} u\right)=f(u), \quad \text { on } \Omega \tag{110}
\end{equation*}
$$

with $\mathscr{B}(x, t, \xi) t \leq 0$ and $f(t) t \geq c t^{q+1}$ for $t \in \mathbb{R}$, then

$$
\begin{equation*}
|u(x)| \leq C \operatorname{dist}(x, \partial \Omega)^{-\frac{p}{q-p+1}} \quad \text { a.e. } x \in \Omega \tag{111}
\end{equation*}
$$

Remark 11.2 In general, inequality (109) is sharp as the following examples show. For $q>\frac{N}{N-2}$ the function $u(x):=c|x|^{-\frac{2}{q-1}}$, for a suitable $c>0$, is a solution of

$$
\Delta u=u^{q} \quad \text { on } \quad \mathbb{R}^{N} \backslash\{0\} .
$$

For $q>1$ the function $u(x):=c x_{1}{ }^{-\frac{2}{q-1}}$, for a suitable $c>0$ is a solution of

$$
\left.\Delta u=u^{q} \quad \text { on } \quad\right] 0,+\infty\left[\times \mathbb{R}^{N-1} .\right.
$$

## 12 Some Liouville theorems for coercive inequalities

In this section we study Liouville theorems for a class of quasilinear elliptic inequalities on $\mathbb{R}^{N}$.

Recently, a wide class of weakly elliptic quasilinear problems were also considered by Farina and Serrin [18]and Pucci and Serrin [38], where sharp interesting cases were handled. The main technique we use throughout this section, is a combination of three ingredients: the Kato inequalities (16) and (18), a slight modification of the test functions method together with an idea introduced in [31].

More precisely, we shall consider problems of the type

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+V(x)|u|^{p-2} u=a(x) f(u) \quad \text { on } \mathbb{R}^{N}, \tag{114}
\end{equation*}
$$

where $V \leq 0$ and $a: \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a nonnegative measurable function. The proof or our main results will be organized in two steps. The first is to apply Kato's inequality (16) and (18) to (114) reducing the problem to the study of the nonnegative solutions of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right) \geq a(x) u^{q}, \quad u \geq 0, \quad \text { on } \mathbb{R}^{N} . \tag{115}
\end{equation*}
$$

A second one will be the application of a priori estimates proved in Section 10 to (115). These estimates depend on two parameters $\alpha$ and $R$. By using an idea first introduced in [31, see proof of Theorem 4.1], we can choose $\alpha$ large enough and then by letting $R \rightarrow+\infty$ we conclude.

We point out that when dealing with equations or inequalities other fine techniques based on Keller and Osserman ideas ([26] and [36] respectively) are available. However, the application of these later ideas need special stronger assumptions on the differential operator and on the nonlinearity. For recent contribution see [33, 20, 28].

Throughout this section we shall assume that $\mathscr{A}$ is $\mathbf{W}-p-\mathbf{C}$ with $p>1$, the vector field $\nabla_{L}$ satisfies (6) (that is $\nabla_{L}$ is homogeneous of degree one with respect to a dilation $\delta_{R}$ as specified in Section 1) and $|\cdot|_{L}$ stands for a homogeneous norm.

Theorem 12.1 Let $V \in L_{\text {loc }}^{\infty}\left(\mathbb{R}^{N}\right)$ be such that $V \leq 0$. Suppose that $f \in \mathscr{C}(\mathbb{R})$ satisfies

$$
f(t) \geq c t^{q}, \quad \text { for } \quad t>0
$$

where $q>p-1$ and $c>0$. Assume that there exists $\bar{\alpha}>1$ such that $a^{-\frac{\bar{\alpha}+p-1}{q-p+1}} \in L_{l o c}^{1}\left(\mathbb{R}^{N}\right)$ and

$$
\begin{equation*}
\liminf _{R \rightarrow+\infty} R^{-p \frac{q+\bar{\alpha}}{q-p+1}} \int_{A_{R}} a^{-\frac{\bar{\alpha}+p-1}{q-p+1}}<+\infty . \tag{116}
\end{equation*}
$$

Let $u$ be a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+V(x)|u|^{p-2} u \geq a(x) f(u) \quad \text { on } \mathbb{R}^{N} . \tag{117}
\end{equation*}
$$

Then $u \leq 0$ a.e. on $\mathbb{R}^{N}$.
Moreover if

$$
f(t) t \geq c|t|^{q+1} \quad t \in \mathbb{R}
$$

and $u$ is a weak solution of the equation

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+V(x)|u|^{p-2} u=a(x) f(u) \quad \text { on } \mathbb{R}^{N}, \tag{118}
\end{equation*}
$$

then $u \equiv 0$ a.e. on $\mathbb{R}^{N}$.

Theorem 12.4 Let $\mathscr{A}=\mathscr{A}\left(x, \nabla_{L} u\right)$ and let $V \in L_{\text {loc }}^{\infty}\left(\mathbb{R}^{N}\right)$ be such that $V \leq 0$. Assume that there exist $q>p-1$ and $\bar{\alpha}>1$ such that $a^{-\frac{\bar{\alpha}+p-1}{q-p+1}} \in L_{l o c}^{1}\left(\mathbb{R}^{N}\right)$ and (116) holds. Suppose that $f \in \mathscr{C}(\mathbb{R})$ satisfies

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} \frac{f(t)}{t^{q}}>0 \tag{120}
\end{equation*}
$$

Then,

1. If $u$ is a weak solution of inequality (117), then $u \leq \max (Z(f) \cup\{0\})^{7}$ a.e. on $\mathbb{R}^{N}$.
2. If $V \equiv 0$ and $u$ is a weak solution of inequality (117), then $u \leq \max Z(f)$ a.e. on $\mathbb{R}^{N}$ 。
3. If $V \equiv 0$ and $f$ is positive, then inequality (117) has no weak solutions.
4. If $V \equiv 0$ and $u$ is a weak solution of equation (118) with $f$ satisfying

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} \frac{f(t)}{|t|^{q}}>0, \quad \limsup _{t \rightarrow-\infty} \frac{f(t)}{|t|^{q}}<0 \tag{121}
\end{equation*}
$$

then,

$$
\min Z(f) \leq u \leq \max Z(f) \quad \text { a.e. on } \mathbb{R}^{N}
$$

Corollary 12.6 Let $\mathscr{A}=\mathscr{A}\left(x, \nabla_{L} u\right)$ and $V \in L_{\text {loc }}^{\infty}\left(\mathbb{R}^{N}\right)$ be such that $V \leq 0$. Let a be a continuous positive function satisfying

$$
a(x) \geq c|x|_{L}^{-\theta} \quad \text { for }|x|_{L} \text { large },
$$

with $\theta<p$. Let $f \in \mathscr{C}(\mathbb{R})$ be such that (120) holds for some $q>p-1$. Then,

1. If $u$ is a weak solution of inequality (117), then $u \leq \max (Z(f) \cup\{0\})$ a.e. on $\mathbb{R}^{N}$.
2. If $V \equiv 0$ and $u$ is a weak solution of inequality (117), then $u \leq \max Z(f)$ a.e. on $\mathbb{R}^{N}$.
3. If $V \equiv 0$ and $f$ is positive, then inequality (117) has no weak solutions.
4. If $V \equiv 0$ and $u$ is a weak solution of equation (118) with $f$ satisfying (121), then,

$$
\min Z(f) \leq u \leq \max Z(f) \quad \text { a.e. on } \mathbb{R}^{N} .
$$

Theorem 12.10 Assume that $\nabla_{L}$ is the usual gradient $\nabla$ on $\mathbb{R}^{N}$ or the horizontal gradient on the Heisenberg group $\mathbb{H}^{n}\left(=\mathbb{R}^{2 n+1}=\mathbb{R}^{N}\right)$. Let $f \in \mathscr{C}(\mathbb{R})$ be such that:
for some $c>0 f$ is nondecreasing, positive on $\left[c,+\infty\left[\right.\right.$ and $\int_{c}^{+\infty}\left(\int_{c}^{t} f(s) d s\right)^{-\frac{1}{p}} d t<+\infty$.
Assume that $V \in L_{l o c}^{\infty}\left(\mathbb{R}^{N}\right)$ satisfies $V \leq 0$.
Then,

1. If $u$ is a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\left|\nabla_{L} u\right|^{p-2} \nabla_{L} u\right)+V(x)|u|^{p-2} u \geq f(u) \quad \text { on } \quad \mathbb{R}^{N} \tag{125}
\end{equation*}
$$

then $u \leq \max (Z(f) \cup\{0\})$ a.e. on $\mathbb{R}^{N}$.
2. If $V \equiv 0$ and $u$ is a weak solution of (125), then $u \leq \max Z(f)$ a.e. on $\mathbb{R}^{N}$.
3. If $V \equiv 0$ and $f$ is positive, then (125) has no weak solutions.
4. If $u$ is a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\left|\nabla_{L} u\right|^{p-2} \nabla_{L} u\right)=f(u) \quad \text { on } \quad \mathbb{R}^{N} \tag{126}
\end{equation*}
$$

with $f$ and $\bar{f}(t):=-f(-t)$ satisfying (124), then

$$
\min Z(f) \leq u \leq \max Z(f) \quad \text { a.e. on } \mathbb{R}^{N}
$$

## 15 Schrödinger's equations and inequalities

In this section we shall study nonexistence of solutions of Schrödinger's type equations of the form

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+\lambda V(x)|u|^{p-2} u=a(x)|u|^{q-1} u \quad \text { on } \mathbb{R}^{N}, \tag{152}
\end{equation*}
$$

where $\mathscr{A}$ is $\mathbf{W}$ - $p$ - $\mathbf{C}$ and $a, V$ and $\lambda$ will be specified during the course.
Similar problems have been studied in the semilinear case in [7], where nonexistence of solutions of the equation

$$
\begin{equation*}
\Delta u+\lambda V(x) u=f(x, u) \quad \text { on } \quad \mathbb{R}^{N} \backslash\{0\} \tag{153}
\end{equation*}
$$

was proved by reducing to an o.d.e. inequality by applying the spherical mean operator to (153) and using some convexity argument. For our problem (152), a radial reduction in general is not applicable even if the differential operator is linear. So we need to proceed differently.

Being interested in nonexistence theorem for (152), by reduction principles it is enough to consider possible nonnegative solutions. Our results allow us to consider, as special case in the Euclidean setting,

$$
V(x)=\frac{1}{|x|^{p}}, \quad a(x)=\frac{c}{|x|^{\theta}} \quad \text { for }|x| \text { large } .
$$

Considering a more general operator we shall require that

$$
\begin{gather*}
a(x) \geq c \frac{\psi^{k}}{|x|_{L}^{\theta}} \quad \text { for }|x|_{L} \text { large }  \tag{154}\\
C_{1} \frac{\psi^{h}}{|x|_{L}^{\nu}} \geq V(x) \geq C_{2} \frac{\psi^{p}}{|x|_{L}^{p}} \quad \text { for }|x|_{L} \quad \text { large } \tag{155}
\end{gather*}
$$

and a Hardy's inequality holds for the weight $V$, that is there exists $\lambda_{H}>0$ such that

$$
\begin{equation*}
\int_{\mathbb{R}^{N}}\left|\nabla_{L} \phi\right|^{p} \geq \lambda_{H} \int_{\mathbb{R}^{N}} V|\phi|^{p} \quad \text { for any } \phi \in \mathscr{C}_{0}^{1}\left(\mathbb{R}^{N}\right) \tag{156}
\end{equation*}
$$

In what follows, for simplicity, we deal with locally bounded solutions in the setting of Carnot groups. We note that if the function $\mathscr{A}$ is $\mathbf{S}-p$ - $\mathbf{C}$ and $V$ belongs to $L_{\text {loc }}^{Q / p}\left(\mathbb{R}^{N}\right)$ or to the Morrey space $M^{Q /(p-\epsilon)}\left(\mathbb{R}^{N}\right)$ then the positive solutions of $(152)$ belongs $L_{\text {loc }}^{\infty}\left(\mathbb{R}^{N}\right)$. This is due to the fact that for $\mathbf{S}$ - $p$ - $\mathbf{C}$ operator a weak Harnack inequality holds. See [29] for the Euclidean case and [9] for the Carnot group setting.

In this section we endow $\mathbb{R}^{N}$ with a group law such that it becomes a Carnot group. As usual, $\nabla_{L}$ stands for the horizontal gradient as described in Appendix A.

The validity of (156) with $V=\psi^{p} /|\cdot|_{L}^{p}$ is established among other Hardy inequalities in [12].

We notice that in view of the reduction principles stated in Chapter II, it suffices to study nonnegative solutions of the inequality related to (152). Notice that the case $\lambda \leq 0$ has been considered in Section 12. Hence, in what follows we shall focus our attention to the case $\lambda>0$.

Theorem 15.1 Let $Q>p>1$. Let $\mathscr{A}$ be $\mathbf{S}-p-\mathbf{C}$ and let $a, V \in L_{l o c}^{1}\left(\mathbb{R}^{N}\right)$ be nonnegative functions satisfying (154) and (155) with $p \geq \nu>\theta$ and $p \geq h \geq k \geq 0$. Assume that (156) holds and let $\lambda$ be such that $0<\lambda \leq \lambda_{H} k_{1}$ where $\lambda_{H}$ is the best constant in (156) and $k_{1}$ is the constant structure appearing in the definition of S-p-C (see Definition 1.1).

Let $u \in W_{L, l o c}^{1, p}\left(\mathbb{R}^{N}\right) \cap L_{l o c}^{\infty}\left(\mathbb{R}^{N}\right)$ be a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+\lambda V(x) u^{p-1} \geq a(x) u^{q}, \quad u \geq 0, \quad \text { on } \quad \mathbb{R}^{N} \tag{157}
\end{equation*}
$$

If

$$
\begin{equation*}
p-1<q \leq \frac{(Q-\theta)(p-1)+x_{0}(p-\theta)}{Q-p} \tag{158}
\end{equation*}
$$

where $x_{0} \geq 1$ is the unique solution of the equation

$$
(x-1+p)^{p} \lambda=x \lambda_{H} k_{1} p^{p}, \quad x \geq 1,
$$

then $a u \equiv 0$ a.e. on $\mathbb{R}^{N}$. Moreover, if $a>0$ or if $\lambda<\lambda_{H} k_{1}$, then $u \equiv 0$ a.e. on $\mathbb{R}^{N}$.
An interesting consequence of Theorem 5.1 is the following.
Corollary 15.2 Assume that $\mathscr{A}, a, V, \lambda$ and $q$ satisfy the hypotheses of Theorem 15.1. Let $u \in W_{L, l o c}^{1, p}\left(\mathbb{R}^{N}\right) \cap L_{\text {loc }}^{\infty}\left(\mathbb{R}^{N}\right)$ be a weak solution of

$$
\begin{equation*}
\operatorname{div}_{L}\left(\mathscr{A}\left(x, u, \nabla_{L} u\right)\right)+\lambda V(x)|u|^{p-2} u \geq a(x)|u|^{q-1} u, \quad \text { on } \quad \mathbb{R}^{N} . \tag{159}
\end{equation*}
$$

Then au $\leq 0$ a.e. on $\mathbb{R}^{N}$. Moreover, if $\lambda<\lambda_{H} k_{1}$, then $u \leq 0$ a.e. on $\mathbb{R}^{N}$.
すべてに感謝 !

## THANK YOU FOR YOUR ATTENTION！

## GRAZIE A TUTTI！

