

Some known results and open problems related to the covariogram

Gabriele Bianchi

Università di Firenze

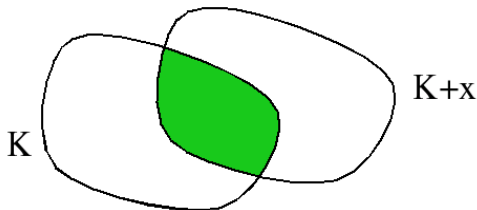
Cortona, June 2011

Definition of covariogram

$K \subset \mathbb{R}^n$ compact set, with $K = \text{cl}(\text{int } K)$

covariogram (or set covariance) of K = function $g_K : \mathbb{R}^n \rightarrow \mathbb{R}$ defined as

$$g_K(x) := \text{vol}(K \cap (K + x)), \quad x \in \mathbb{R}^n$$

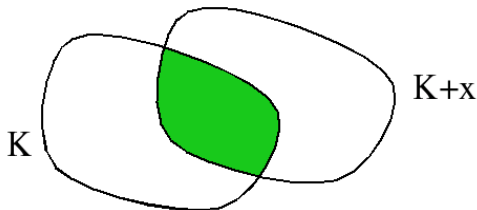


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- g_K is invariant with respect to translations and reflections of K ;
- the covariogram is the autocorrelation of 1_K ,

$$g_K(x) = 1_K * 1_{(-K)}$$

that is, passing to Fourier transforms,

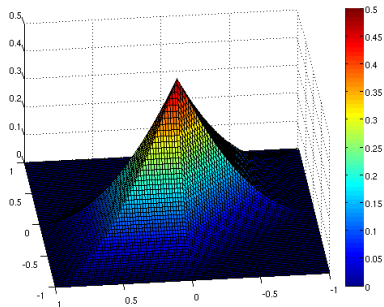
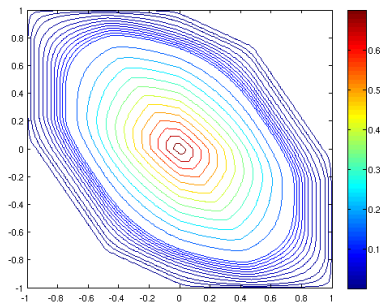
$$\widehat{g}_K(x) = |\widehat{1}_K(x)|^2 \quad \forall x \in \mathbb{R}^n.$$

Structure of talk

- 1 Does g_K determine the set K ? (“Covariogram problem”)
- 2 Which functions are covariograms?
- 3 Which geometric properties of K can be explicitly read in g_K ?
- 4 A view at Question 1 from the Fourier transform side, in complex variables.
 - ▶ Zero sets of Fourier transforms of 1_K

Properties of covariogram: general

- support of g_K is $K + (-K)$;
 - ▶ \implies covariogram gives the width of K in every direction;
- $g_K(0) = \text{vol}(K)$;
- g_K is even;
- when K is convex:
 - ▶ $(g_K)^{1/n}$ is concave (Brunn-Minkowski inequality).



Properties of covariogram: regularity and derivatives

- If K has finite perimeter $\iff g_K$ is Lipschitz;



B. Galerne, Image Anal. and Stereol., 2011.

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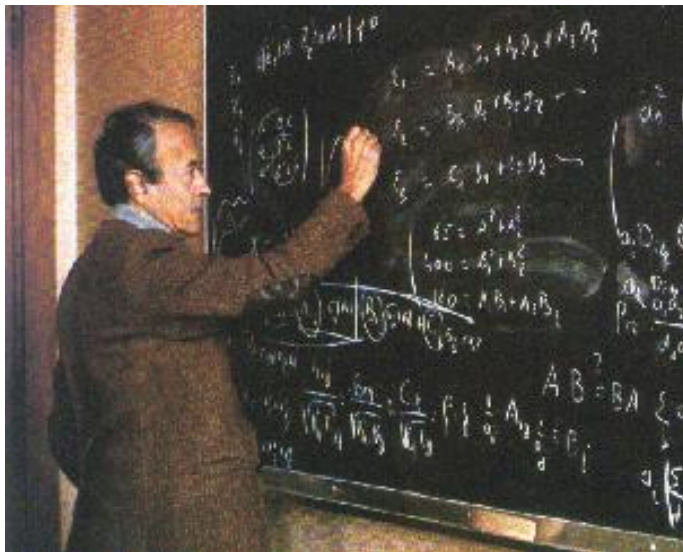
$$-\frac{\partial g_K}{\partial u}(0) = \text{vol}(K|u^\perp) \quad \forall u \in S^{n-1}$$

- ▶ If K is strictly convex $\implies g_K$ is C^1 in $\text{int}(\text{supp } g_K) \setminus \{0\}$;
- ▶ If K is C^1 $\implies g_K$ is C^2 in $\text{int}(\text{supp } g_K) \setminus \{0\}$;
- ▶ explicit formulae for ∇g_K and $D^2 g_K$



Meyer, Reisner and Schmuckenslager, Mathematika (1993).

G. Matheron and mathematical morphology



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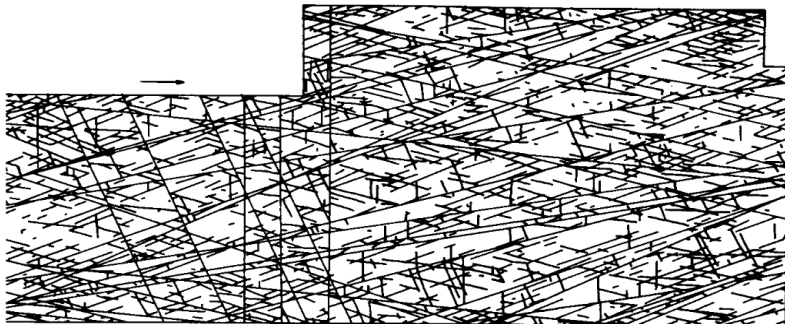


Figure IX.4. Simulation of geological faults.

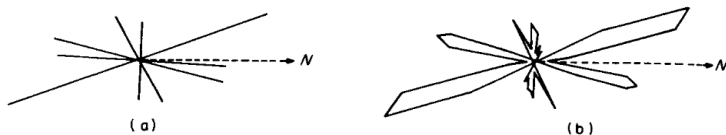




Figure IX.5. Rose of directions of the simulation on Fig. IX-4(a), and its estimation (b).

Section 1

Covariogram problem

Does g_K determine the set K ?

-  G. Matheron, Le covariogramme géométrique des compacts convexes de \mathbb{R}^2 (1986).
-  R. Adler and R. J. Pyke, Inst. Math. Statistics Bull. (1991).

Results for Covariogram Problem I

Non-convex sets

In general **NO**



Rosenblatt and Seymour (1982); Gardner, Gronchi and Zhong (2005).

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Convex sets in \mathbb{R}^2

YES



G. Averkov and G. Bianchi, J. Eur. Math. Soc. (2009).



Other contributions from W. Nagel, G. Bianchi, F. Segala, A. Volčič.

Results for Covariogram Problem II

Convex Polytopes in any dimension

- **YES** for any **generic** polytope in \mathbb{R}^n , for any n



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- **YES** in \mathbb{R}^3



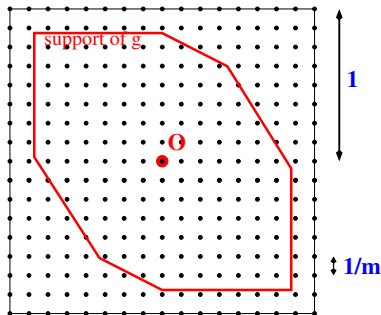
G. Bianchi, Adv. Math. (2009).

Covariogram problem: Algorithm for reconstruction



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INPUT knowledge, affected by a random error, of g_K at all points of a grid containing $\text{supp } g_K$



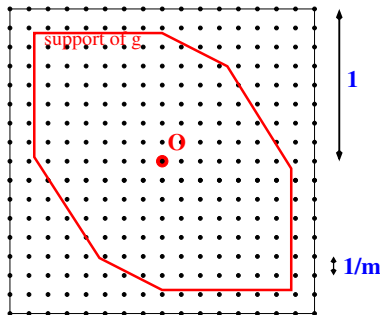
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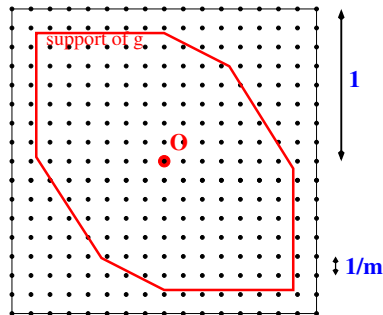
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Theorem

Assume that $K \subset \mathbb{R}^n$ is a convex body determined by its covariogram. Then, as $m \rightarrow \infty$ (i.e. the grid gets finer and finer), almost surely,

$$P_m \rightarrow K \quad \text{or} \quad P_m \rightarrow -K.$$

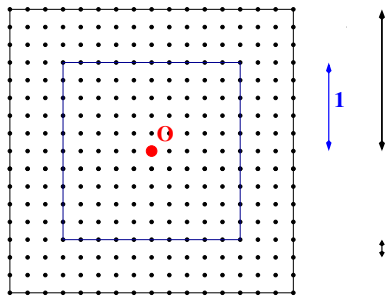
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Some open problems:

- Polytopes: fill the gap (other counterexamples and positive results)
- **Explicit** stability estimates of the map $g_K \rightarrow K$ (when it is injective)
 - ▶ estimates needed to obtain convergence rates in the previous algorithm
- C_+^2 convex bodies: open even in dimension 3

Case of C_+^2 convex bodies in \mathbb{R}^n , $n \geq 3$

For each $u \in S^{n-1}$ let us consider the “Hessian matrix” of h_K :

$$A_K(u) := \nabla^2 h_K(u) + h_K(u)I.$$

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- asymptotic behav. of g_K near point of $\text{supp } g_K$ with outer normal u :

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Therefore we know:

- 1 $\implies A_K(u) + A_K(-u)$
- 2 $\implies \det A_K(u) + \det A_K(-u)$
- 3 $\implies \det (A_K(u)^{-1} + A_K(-u)^{-1})$

C_+^2 convex: information easily readable

The information that is easily readable in g_K is thus:

- 1 $A_K(u) + A_K(-u)$ (i.e. the even part of h_K)
- 2 the **non-ordered** set $\{\text{Gauss}_K(u), \text{Gauss}_K(-u)\}$

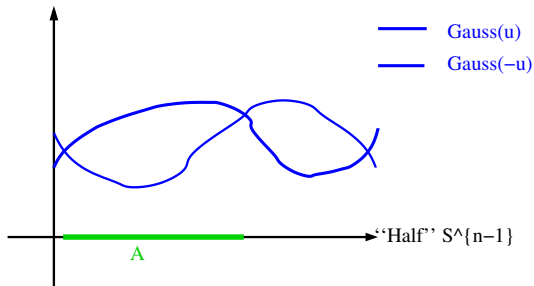
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- Not enough information to fully determine both matrices $A(u)$ and $A(-u)$ (In \mathbb{R}^3 we have “6 unknowns and only 5 conditions”);
- For particular subclasses of C_+^2 convex bodies this difficulty can be overcome (bodies with analytic boundaries; bodies of revolution)

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- A. Fish, D. Ryabogin and A. Zvavitch

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 - ▶ any $n \geq 2$ and $K \in \mathcal{C}_+^2$ (it is a consequence of some formula presented in the previous slides:

the set $\{\text{Gauss}_K(u), \text{Gauss}_K(-u)\}$ does not depend on $u \in S^{n-1}$

and continuity implies that Gauss_K is constant).

Proof of “radial g_K implies radial K ”

Theorem

Assume $f \in L^2(\mathbb{R}^n)$, $n \geq 2$, **real valued** and with compact support. Assume that

$$|\widehat{f}|(x) \quad \text{is a radial function for } x \in \mathbb{R}^n.$$

Then f is a translation of a radial function.

Moreover f is determined in $L^2(\mathbb{R}^n)$ by $|\widehat{f}|$, up to translations.

 W. Lawton, J. Opt. Soc. Am. (1981)

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where $m \in \mathbb{N}$, $c \in \mathbb{C}$, $x_0 \in \mathbb{R}^n$, (λ_j) is a sequence in \mathbb{C} .

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where $m \in \mathbb{N}$, $c \in \mathbb{C}$, $x_0 \in \mathbb{R}^n$, (λ_j) is a sequence in \mathbb{C} .

- theorem false if f is complex valued

Which radial functions are covariograms?

Consequences:

- a radial function h is the covariogram of a **convex** set if and only if

$$h(x) = R^n g_{B(o,1)}\left(\frac{x}{R}\right) \quad \text{for } R = \frac{1}{2} \left(\frac{\text{vol}(\text{supp } h)}{\text{vol}(B(o,1))} \right)^{\frac{1}{n}}.$$

- reduction of the corresponding problem for general set to a one-dimensional problem

Section 3

Which geometric properties of K can be explicitly read in g_K ?

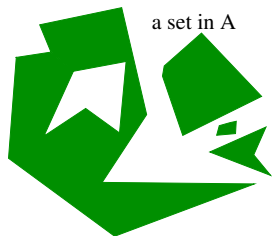
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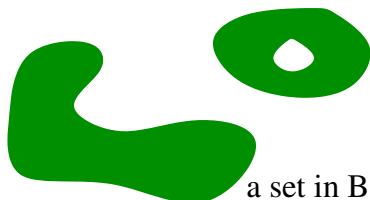
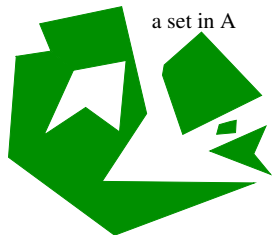
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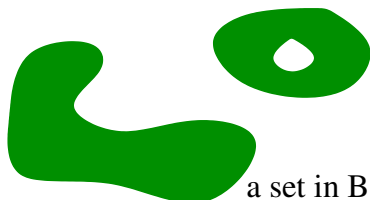
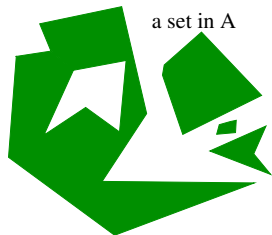
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Theorem

Assume a-priori that g_K is the covariogram of a set in $\mathcal{A} \cup \mathcal{B}$.

Then there are explicitly computable properties of g_K that determine whether K is convex or not.



Benassi, Bianchi and D'Ercole, Mathematika (2010).

Determine whether the set is convex or not: test

First test (for class \mathcal{B}) : Check whether, for each $u \in S^1$, it is

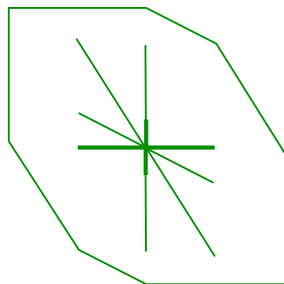
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Second test (for class \mathcal{A}) : Check certain properties of the **set of discontinuities of ∇g_K**



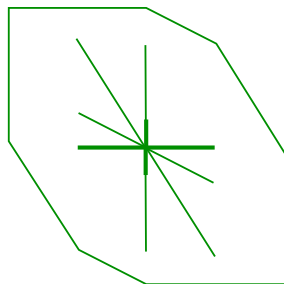
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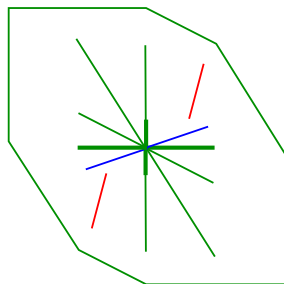
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Convex



Non-convex

Recognize other properties

Theorem. Central symmetry

Let $K \subset \mathbb{R}^n$ be a regular compact set.

The set K is **convex and centrally symmetric** if and only if

$$g_K(o) = \frac{1}{2} (\text{vol}(\text{supp } g_K))^{\frac{1}{n}}$$

When this holds $K = (1/2)\text{supp } g_K$.

- A consequence of Brunn-Minkowski inequality and its equality cases.

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Theorem. Central symmetry

Let $K \subset \mathbb{R}^n$ be a regular compact set.

The set K is **convex and centrally symmetric** if and only if

$$g_K(o) = \frac{1}{2} (\text{vol}(\text{supp } g_K))^{\frac{1}{n}}$$

When this holds $K = (1/2)\text{supp } g_K$.

- A consequence of Brunn-Minkowski inequality and its equality cases.

Theorem. Homothetic level lines of g_K

Let $K \subset \mathbb{R}^n$ be a centrally symmetric convex body. Assume that the level lines $\{x : g_K(x) = t\}$ are homothetic to each other for all $t > 0$ small. Then K is an ellipsoid.



Meyer, Reisner and Schmuckenslager, *Mathematika* (1993).

- Connections with floating bodies.

Some open problems

Convexity or not It is known that when $K \subset \mathbb{R}^2$ is convex then $\sqrt{g_K}$ is concave on its support.

Does this property characterize the convexity of K in the class of planar regular compact set (or in some subclass)?

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Central symmetry Assume K non-convex. Is it possible to read in g_K whether K is centrally symmetric or not?

Homothetic level lines (MRS result) Is the central symmetry of K necessary? Is it sufficient to assume that only two level lines are homothetic?

Section 4

A view at the covariogram problem from the Fourier transform side, in complex variables.

-  J. L. C. Sanz and T. S. Huang, J. Math. Anal. Appl. (1984).
-  N. E. Hurt, Phase retrieval and zero crossing (1989).
-  T. Kobayashi, J. Fac. Sci. Univ. Tokyo Sect. IA Math. (1989).



Phase Retrieval?

Phase Retrieval in complex variables

Fourier transform in \mathbb{C}^n

Let $f \in L^2(\mathbb{R}^n)$ with compact support. Define, for $z \in \mathbb{C}^n$,

$$\widehat{f}(z) = \int_{\mathbb{R}^n} e^{ix \cdot z} f(x) dx.$$

FACT: \widehat{f} is an holomorphic function *of exponential type*.

- “*of exponential type*” means that $|\widehat{f}(z)| \leq ae^{b\|z\|}$ for some $a, b \in \mathbb{C}$ and all $z \in \mathbb{C}^n$

Phase Retrieval in \mathbb{C}^n : role of factorization

Theorem. J. Sanz and T. Huang, J. Math. Anal. Appl. (1984)

Let $f \in L^2(\mathbb{R}^n)$ with compact support. If \widehat{f} is irreducible in \mathbb{C}^n then f is determined by the knowledge of $|\widehat{f}(x)|$ for $x \in \mathbb{R}^n$.

(\widehat{f} is irreducible in \mathbb{C}^n if it cannot be written as $\widehat{f} = f_1 f_2$, with f_1 and f_2 holomorphic entire functions, both with non-empty zero sets.)

Theorem. R. Barakat and G. Newsam, J. Math. Phys. (1984)

Let $f, g \in L^2(\mathbb{R}^2)$ with compact support. If $f \neq g$ and $|\widehat{f}(x)| = |\widehat{g}(x)|$ for each $x \in \mathbb{R}^2$, then, for all $z \in \mathbb{C}^2$,

$$\widehat{f}(z) = f_1(z) f_2(z) \quad \text{and} \quad \widehat{g}(z) = e^{i c \cdot z} f_1(z) \overline{f_2(\bar{z})},$$

for suitable holomorphic functions f_1 and f_2 , both with non-empty zero set.

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for suitable holomorphic functions f_1 and f_2 , both with non-empty zero set.

- The only known example of different convex sets with equal covariogram are $K_1 \times K_2$ and $K_1 \times (-K_2) \subset \mathbb{R}^n \times \mathbb{R}^m$. In Fourier space this corresponds to the phenomenon described in the Theorem.

Phase Retrieval in \mathbb{C}^n : zero set of $\widehat{1}_K(z)$

Theorem

Any $f \in L^2(\mathbb{R}^n)$ with compact support is determined, up to a translation, by the knowledge of

- 1) the *modulus of its FT*, $|\widehat{f}(x)|$, for $x \in \mathbb{R}^n$;
- 2) the *zero set of its FT*, $\{z \in \mathbb{C}^n : \widehat{f}(z) = 0\}$.

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Question

Regarding the covariogram problem, what do we know about

$$\{z \in \mathbb{C}^n : \widehat{1_K}(z) = 0\}?$$

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Regarding the covariogram problem, what do we know about

$$\{z \in \mathbb{C}^n : \widehat{1_K}(z) = 0\}?$$

- The identity $g_K = 1_K * 1_{-K}$ seen in \mathbb{C}^n becomes

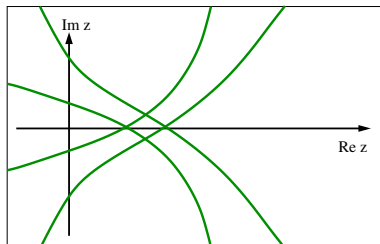
$$\widehat{g_K}(z) = \widehat{1_K}(z) \overline{\widehat{1_K}(\bar{z})} \quad \forall z \in \mathbb{C}^n. \quad (1)$$

Thus we have:

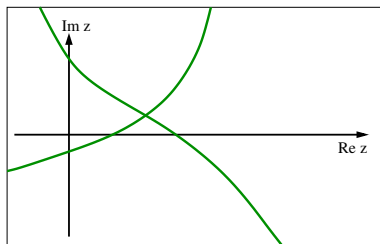
$$\text{zero set of } \widehat{g_K} = (\text{zero set of } \widehat{1_K}) \cup \overline{(\text{zero set of } \widehat{1_K})}$$

summarizing...

$$\text{zero set of } \widehat{g}_K = (\text{zero set of } \widehat{1}_K) \cup \overline{(\text{zero set of } \widehat{1}_K)}$$



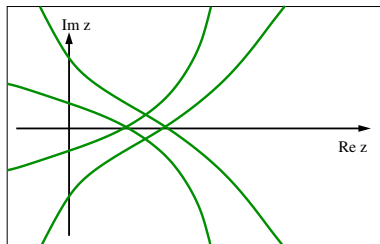
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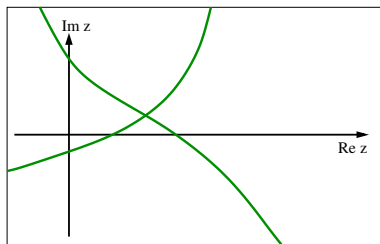
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zero set of \widehat{g}_K



zero set of $\widehat{1}_K$

To determine $\widehat{1}_K$ it suffices:

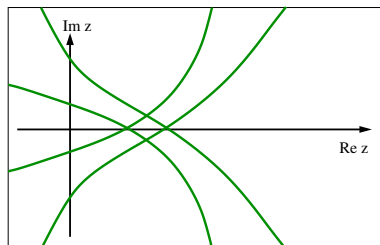
- modulus of $\widehat{1}_K(x)$ for x real
- zero set of $\widehat{1}_K$ in \mathbb{C}^n

The knowledge of g_K gives us

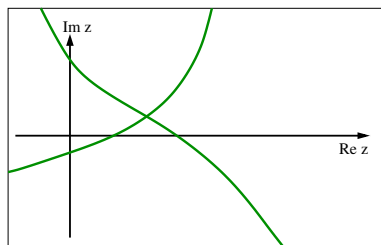
- modulus of $\widehat{1}_K(x)$ for x real
- (zero set of $\widehat{1}_K$ in \mathbb{C}^n) \cup (its conjugate)

summarizing...

$$\text{zero set of } \widehat{g}_K = (\text{zero set of } \widehat{1}_K) \cup \overline{(\text{zero set of } \widehat{1}_K)}$$



zero set of \widehat{g}_K



zero set of $\widehat{1}_K$

To determine 1_K it suffices:

- modulus of $\widehat{1}_K(x)$ for x real
- zero set of $\widehat{1}_K$ in \mathbb{C}^n

The knowledge of g_K gives us

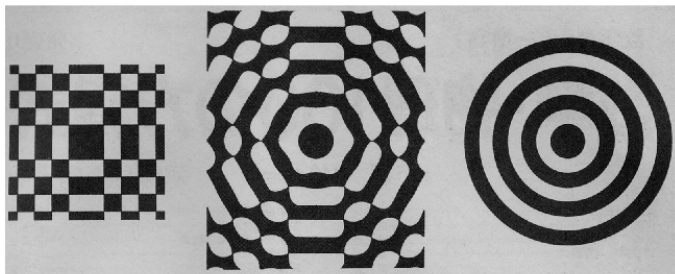
- modulus of $\widehat{1}_K(x)$ for x real
- (zero set of $\widehat{1}_K$ in \mathbb{C}^n) \cup (its conjugate)

- Passing from $K_1 \times K_2$ to $K_1 \times (-K_2) \implies$ substituting zeros of $\widehat{1}_{K_2}$ with their conjugates and leaving others zeros unchanged.

Kobayashi study of the zero set of $\widehat{1}_K$, for K convex



T. Kobayashi, J. Fac. Sci. Univ. Tokyo Sect. IA Math. (1989).



イ) Ω は正方形

ロ) Ω は正六角形

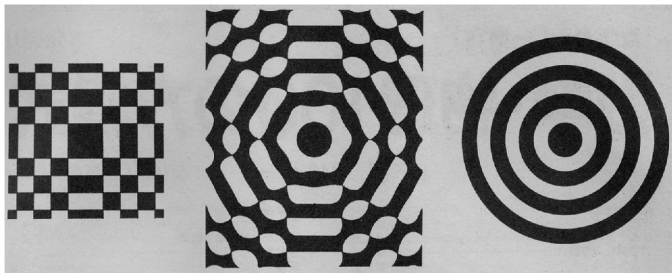
ハ) Ω は円板

- Image represents the restriction to \mathbb{R}^2 (i.e. $\{\text{Im } z = 0\}$) of $\widehat{1}_K$ (which is real valued because K is o -symmetric);
- zero set = boundary between white and black regions;
- different behaviours:
 - ▶ Square : Zero set is non-compact and connected, it factors;
 - ▶ Ball: Zero set has countably many connected components.

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K=Square

Hexagon

Circle

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zero set of $\widehat{1}_K$, for K convex, smooth, with $\text{Gauss}_K > 0$
 Kobayashi proves that when K is convex, smooth enough and with
 $\text{Gauss}_K > 0$ the asymptotic behaviour is similar to that of a ball.

Define a subset S of \mathbb{C}^n :

$$S = "S^{n-1} \times \mathbb{C}" = \{z \in \mathbb{C}^n : z = \lambda u + i\mu u, \text{ with } \lambda, \mu \in \mathbb{R}, u \in S^{n-1}\}$$

Theorem

$$\exists m_0 \in \mathbb{N} : \quad (\text{zero set of } \widehat{1}_K) \cap S = (\text{compact set}) \cup \left(\bigcup_{j=m_0}^{\infty} \mathcal{Z}_j \right)$$

and each \mathcal{Z}_j is a regular submanifold in S ($\subset \mathbb{C}^n$) diffeomorphic to S^{n-1} .

Moreover

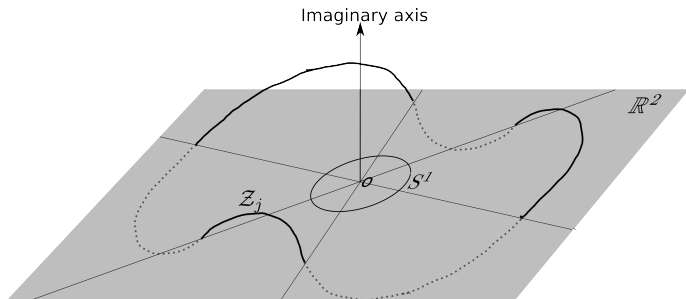
$$\mathcal{Z}_j = \{F_j(u)u : u \in S^{n-1}\}$$

with, as $j \rightarrow \infty$,

$$F_j(u) = \frac{\pi(2j + n - 1)}{\text{width}_K(u)} + i \log \left(\frac{\text{Gauss}_K(u)}{\text{Gauss}_K(-u)} \right) + O\left(\frac{1}{j}\right).$$

shape of the components at ∞ of zero set of $\widehat{1}_K$

$$\mathcal{Z}_j : u \in S^{n-1} \rightarrow \left(\frac{\pi(2j+n-1)}{\text{width}_K(u)} + \mathbf{i} \log \left(\frac{\text{Gauss}_K(u)}{\text{Gauss}_K(-u)} \right) + O\left(\frac{1}{j}\right) \right) u.$$



- ∞ similar copies; each of them carries the same information;
- \mathcal{Z}_j intersects \mathbb{R}^n (i.e. $\text{Im } z = 0$) for u such that $\text{Gauss}_K(u) = \text{Gauss}_K(-u)$;
- g_K gives us $\mathcal{Z}_j \cup \overline{\mathcal{Z}_j}$, and we need from this to determine \mathcal{Z}_j
 - ▶ the ambiguity is where \mathcal{Z}_j and $\overline{\mathcal{Z}_j}$ meet: that is in $\mathcal{Z}_j \cap \mathbb{R}^n$ (again u such that $\text{Gauss}_K(u) = \text{Gauss}_K(-u)$!!!!!!)

Does the zero set alone determine K ?

- The paper by Kobayashi tries to understand whether the (asymptotics of the) zero set alone does determine K .
- His formula proves that this zero set determines, for each $u \in S^{n-1}$,

$$\text{width}_K(u) \quad \text{and} \quad \frac{\text{Gauss}_K(u)}{\text{Gauss}_K(-u)}.$$

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Theorem (Kobayashi)

Assume K *planar* “smooth enough” convex body with $\text{Gauss}_K > 0$. The asymptotic behaviour of the set

$$(\text{zero set of } \widehat{1}_K) \cap S$$

determines K , up to translations.

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Problem

What about dimension $n \geq 3$?