

## On a unusual application of ODEs to solve linear systems

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We deal with the solution of the (possibly) ill-conditioned linear system

$$Ac = b \tag{1}$$

where  $A \in \mathbb{R}^N \times N$  is a bounded linear operator in a Hilbert space  $H$ ,  $c \in \mathbb{R}^N$ ,  $b \in \mathbb{R}^N$ .

The method proposed in this paper is based on the approach called Dynamical Systems Method (*DSM*), suggested by A. Ramm in [1], and later, e.g. in [2].

The DSM method for solving (1) consists of solving the Cauchy problem

$$x'(t) = \Theta(t, x(t)), \quad x(0) = x_0$$

where  $x_0 \in H$  is an arbitrary element of a Hilbert space  $H$  and  $\Theta$  is a nonlinear function, chosen so that the following conditions hold: a) there exists a unique solution  $x(t) \forall t \geq 0$ , b) there exists  $x(\infty)$  such that  $A(x(\infty)) = b$  and  $x(\infty) = c$ . Usually, the DSM method chooses  $\Theta(t, x(t)) = (A^T A + \lambda(t) I)^{-1} A^T b - x(t)$ . Actually, the DSM method shifts the search for the solution of (1) to the calculation of the solution of another problem, which reduces to a vectorial differential equation. Here the novelty consists in introducing a general regularization operator  $B$ , which replaces the identity regularization operator  $I$  in  $\Theta(t, x(t))$ , so that the vectorial differential equation to be solved becomes

$$x'(t) = -x(t) + (A^T A + \lambda(t) B^T B)^{-1} A^T b, \quad x(0) = x_0 \tag{2}$$

Convergence of solution of (2) to solution of (1) is proved. Then (2) is solved by a one-step explicit numerical method, which converges to the solution of (2) in a fast way. Therefore the overall method is characterized by a fast total convergence which achieves competitive value of relative errors in very few steps. Some enlightening numerical examples are presented.

## References

- [1] A.G. Ramm, *Dynamical Systems Method for solving operator equations*, Elsevier, Amsterdam-Boston; 2007
- [2] S. Indratno, A.G. Ramm, Dynamical systems method for solving ill-conditioned linear algebraic systems, *Int. J. Comput. Sci. Math.* 2009; **2**: 308-333