Hydrodynamic limit in the Hyperbolic Space-Time Scale

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 - mechanical equilibrium: constant pressure or tension profiles,

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 - mechanical equilibrium: constant pressure or tension profiles,

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- thermal equilibrium: constant temperature profiles.
- These partial equilibriums may be reached at different time scales: *typically* mechanical equilibrium is reached faster than thermal equilibrium.

Mechanical and Thermal equilibrium

Mechanical Equilibrium is reached in hyperbolic time scales (same rescaling of space and time), and is driven by Euler system of equations (for a compressible gas). It involves the ballistic evolution of the long waves (mechanical modes).

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- When thermal conductivity is finite, Thermal Equilibrium is reached later, in the diffusive time scales (time² = space), and temperature (or thermal energy) profiles evolve following *heat equation*.
- If thermal conductivity is infinite, Thermal Equilibrium is reached in a super-diffusive time scales (time^α = space, α < 2), and typically temperature (or thermal energy) profiles evolve following a *fractional heat equation*.

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Most of non-equilibrium situation are obtained by

- changing boundary conditions in time
- applying boundary conditions corresponding to different equilibrium states, obtaining dynamics that have non-equilibrium stationary states (NESS).

Chain of oscillators

$$\begin{split} \dot{r}_{x}(t) &= p_{x}(t) - p_{x-1}(t), & x = 1, \dots, N \\ \dot{p}_{x}(t) &= V'(r_{x+1}(t)) - V'(r_{x}(t)) & x = 1, \dots, N-1 \\ \dot{p}_{N}(t) &= \tau(t/N) - V'(r_{N}(t)) \\ p_{0}(t) &= 0. \end{split}$$

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$$\begin{aligned} \boldsymbol{\mathcal{E}}_{x} &= \frac{p_{x}^{2}}{2} + V(r_{x}) \\ \dot{\boldsymbol{\mathcal{E}}}_{x} &= p_{x}V'(r_{x+1}) - p_{x-1}V'(r_{x}) \end{aligned}$$

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We are interested in the *macroscopic* evolution of $(r_x(t), p_x(t), \mathcal{E}_x(t))$.

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For $\tau(t) = \tau$ constant in time, a class of stationary measures is given by the Gibbs measures at temperature β^{-1} , tension τ

$$d\mu_{\beta,\tau,p} = \prod_{x=1}^{N} e^{-\beta(\mathcal{E}_x - \tau r_x) - \mathcal{G}(\beta,\tau)} dp_x dr_x$$

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Thermodynamic entropy is

$$S(u,r) = \inf_{\tau,\beta} \{-\beta\tau r + \beta u - \mathcal{G}(\beta,\tau)\}$$
$$\beta(u,r) = \partial_u S(u,r), \qquad \tau(u,r) = -\beta^{-1}\partial_r S(u,r).$$

Ergodicity (of the infinite system)

Consider the corresponding infinite dynamics:

$$\dot{r}_{x}(t) = p_{x}(t) - p_{x-1}(t), \dot{p}_{x}(t) = V'(r_{x+1}(t)) - V'(r_{x}(t))$$
 $x \in \mathbb{Z}$

Theorem

(Fritz, Funaki, Lebowitz, PTRF 1994) Assume that a probability ν is translation invariant, stationary, finite entropy density, and the conditional measure $\nu(dp|r)$ is exchangeable. Then ν is a convex combination of Gibbs measures $d\mu_{\beta,\tau,p}$.

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- Chaoticity of the dynamics, due to the non-linearity of V, should give such ergodic property
- Adding conservative noise (stochastic collisions) to the dynamics one obtain ergodicity.

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3 conserved quantities: we expect the weak convergence to the hyperbolic system of PDE

$$\frac{1}{N} \sum_{x} G(x/N) \begin{pmatrix} r_{x}(Nt) \\ p_{x}(Nt) \\ \mathcal{E}_{x}(Nt) \end{pmatrix} \xrightarrow[N \to \infty]{} \int_{0}^{1} G(y) \begin{pmatrix} r(y,t) \\ p(y,t) \\ e(y,t) \end{pmatrix} dy$$
$$\frac{\partial_{t} r(t,y) = \partial_{y} p(t,y)}{\partial_{t} p(t,y) = \partial_{y} \tau [u(t,y), r(t,y)]}$$
$$\frac{\partial_{t} e(t,y) = \partial_{y} (\tau [u(t,y), r(t,y)] p(t,y))$$

where $u = e - p^2/2$: internal energy. and, for smooth solutions, the boundary conditions:

$$p(t,0) = 0, \qquad \tau[u(t,1),r(t,1)] = \tau(t)$$

Euristics

take $G:[0,1] \rightarrow \mathbb{R}$ with compact support in (0,1),

$$\frac{d}{dt}\frac{1}{N}\sum_{x}G(x/N)\begin{pmatrix}r_{x}(Nt)\\p_{x}(Nt)\\\mathcal{E}_{x}(Nt)\end{pmatrix} = \sum_{x}G(x/N)\begin{pmatrix}\nabla p_{x-1}(Nt)\\\nabla V'(r_{x}(Nt))\\\nabla \left[p_{x}(Nt)V'(r_{x}(Nt)\right]\end{pmatrix}$$
$$\sim -\frac{1}{N}\sum_{x}G'(x/N)\begin{pmatrix}p_{x}(Nt)\\V'(r_{x}(Nt))\\p_{x}(Nt)V'(r_{x}(Nt))\end{pmatrix}$$

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assuming local equilibrium, we have

$$\sim -\int_0^1 G'(y) \begin{pmatrix} p(t,y) \\ \tau(u(t,y),r(t,y)) \\ p(t,y)\tau(u(t,y),r(t,y)) \end{pmatrix} dy$$

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Note that $y \in [0,1]$ is the material (Lagrangian) coordinate.

Results with conservative stochastic dynamics

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Results with conservative stochastic dynamics

- To prove some form of *local equilibrium* we need to add stochastic terms to the dynamics (the deterministic non-linear case is too difficult).
- Random exchanges of velocities between nearest neighbor particles, conserve energy, momentum and volume, destroying all other (possible) conservation laws. It provides the *right ergodicity* property.
- With such noise in the dynamics, for smooth solutions the HL is proven in:
 - N. Even, S.O., ARMA (2014) (with boundary conditions),
 - S.O., SRS Varadhan, HT Yau, CMP (1993) (periodic bc).

This is an example of a non-ergodic dynamics:

$$V(r) = r^2/2$$

in fact it is a completely integrable dynamics:

$$\dot{q}_x = p_x, \qquad \dot{p}_x = \Delta q_x = q_{x+1} + q_{x-1} - q_x,$$

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Take here $x = 1, \ldots, N$,

$$\hat{f}(k) = \sum_{x} f_{x} e^{i2\pi kx}$$
 $k \in \{0, 1/N, \dots, (N-1)/N\}$

 $\omega(k) = 2|\sin(\pi k)|$ dispersion relation:

$$\mathcal{H} = \sum_{x} \boldsymbol{\mathcal{E}}_{x} = \frac{1}{2N} \sum_{k} \left[\omega(k)^{2} |\hat{\boldsymbol{q}}(k)|^{2} + |\hat{\boldsymbol{p}}(k)|^{2} \right]$$

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$$\frac{d}{dt}\hat{\psi}(t,k) = -i\omega(k)\hat{\psi}(t,k) \qquad \qquad \hat{\psi}(t,k) = e^{-i\omega(k)t}\hat{\psi}(0,k)$$
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Harmonic Oscillators Chain: Quantum Dynamics

$$p_{x} = -i\partial_{q_{x}} = -i(\partial_{r_{x+1}} - \partial_{r_{x}})$$
$$\mathcal{E}_{x} = \frac{1}{2}(p_{x}^{2} + r_{x}^{2})$$
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Heisenber evolution $\frac{d}{dt}A(t) = i[\mathcal{H}, A(t)]$

$$a_k(t) = e^{-i\omega(k)t}a_k, \qquad a_k^*(t) = e^{-i\omega(k)t}a_k^*.$$

Consider the chain in *thermal* equilibrium: initial distribution with covariances

$$\left\langle r_x(0); r_{x'}(0) \right\rangle = \left\langle p_x(0); p_{x'}(0) \right\rangle = \beta^{-1} \delta_{x,x'}, \qquad \left\langle q_x; p_{x'} \right\rangle = 0,$$

for some inverse temperature β , while in *mechanical local* equilibrium:

$$\langle r_{[Ny]}(0) \rangle \longrightarrow r(0,y), \quad \langle p_{[Ny]}(0) \rangle \longrightarrow p(0,y).$$

Harmonic Chain: Thermal Equilibrium (classic case)

thermal equilibrium is conserved by the dynamics: for any $t \ge 0$

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Proof.

Thermal equilibrium is Fourier space is:

$$\langle \hat{\psi}(k,0)^*; \hat{\psi}(k',0) \rangle = 2\beta^{-1}\delta(k-k'), \qquad \langle \hat{\psi}(k,0); \hat{\psi}(k',0) \rangle = 0.$$

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Consequently

$$\left\{ \hat{\psi}(k,t)^{*}; \hat{\psi}(k',t) \right\} = e^{i(\omega(k)-\omega(k'))t} \left\{ \hat{\psi}(k,0)^{*}; \hat{\psi}(k',0) \right\} = 2\beta^{-1}\delta(k-k') \\ \left\{ \hat{\psi}(k,t); \hat{\psi}(k',t) \right\} = e^{-i(\omega(k)+\omega(k'))t} \left\{ \hat{\psi}(k,0); \hat{\psi}(k',0) \right\} = 0.$$

Harmonic Chain: Thermal Equilibrium implies Euler Equation limit

 $r_{[N_Y]}(Nt)$ and $p_{[N_Y]}(Nt)$ converge weakly to the solution of the linear wave equation

 $\partial_t \mathbf{r}(y,t) = \partial_y \mathbf{p}(y,t), \qquad \partial_t \mathbf{p}(y,t) = \partial_y \mathbf{r}(y,t).$

This is the Euler equation for this system since here $\tau(u, r) = r$.
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This is the Euler equation for this system since here $\tau(u, r) = r$. For the energy, because of the thermal equilibrium, for any $t \ge 0$:

$$\langle \mathcal{E}_{x}(t) \rangle = \beta^{-1} + \frac{1}{2} \left(\langle p_{x}(t) \rangle^{2} + \langle r_{x}(t) \rangle^{2} \right)$$

$$\left(\mathcal{E}_{[Ny]}(Nt) \right) \longrightarrow \mathbf{e}(y,t) = \beta^{-1} + \frac{1}{2} \left(\mathbf{p}^2(y,t) + \mathbf{r}^2(y,t) \right),$$

$$\partial_t \mathbf{e}(y,t) = \partial_y \left(\mathbf{p}(y,t) \mathbf{r}(y,t) \right).$$

Quantum Harmonic Chain: Thermal Equilibrium

Initial density matrix ho_{eta} , define

$$\langle A \rangle = tr(A\rho_{\beta}), \langle A; B \rangle = \langle AB \rangle - \langle A \rangle \langle B \rangle$$

such that

$$\langle r_x(0); r_{x'}(0) \rangle = \langle p_x(0); p_{x'}(0) \rangle = C_\beta(x-x'), \qquad \langle q_x; p_{x'} \rangle = \frac{1}{2}\delta(x-x')$$

$$C_{\beta}(x) = \frac{1}{N} \left[\beta^{-1} + \sum_{k \neq 0} e^{2\pi i k x} \left(\frac{\omega_k}{e^{\beta \omega_k} - 1} + \frac{\omega_k}{2} \right) \right]$$
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$$\left\{ \mathcal{E}_{[Ny]} \right\} \longrightarrow \mathbf{e}(y) = \bar{C}(\beta) + \frac{1}{2} \left(\mathbf{p}^2(y) + \mathbf{r}^2(y) \right),$$

$$\bar{C}(\beta) = \int_0^1 \omega(k) \left(\frac{1}{e^{\beta \omega(k)} - 1} + \frac{1}{2} \right) dk \underset{\beta \to 0}{\sim} \beta^{-1}$$

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The argument fails dramatically if the system is not in thermal equilibrium, even local thermal Gibbs

$$\langle r_{x}(0); r_{x'}(0) \rangle = \langle p_{x}(0); p_{x'}(0) \rangle = \beta^{-1} \left(\frac{x}{N}\right) \delta_{x,x'}, \quad \langle q_{x}(0); p_{x'}(0) \rangle = 0$$
(2)

is not conserved, and correlations between $p_x(t)$ and $r_x(t)$ build up in time.

No autonomous macroscopic equation for the energy!

There are infinite many conservation laws.

Wigner distribution

$$\begin{split} \xi \in \mathbb{R}, \ k \in [0,1], \\ \widehat{W}_{N}(\xi,k,t) &:= \frac{2}{N} \left(\hat{\psi}^{*} \left(Nt, k - \frac{\xi}{2N} \right) \hat{\psi} \left(Nt, k + \frac{\xi}{2N} \right) \right) \\ W_{N}(y,k,t) &= \int \widehat{W}_{N}(t,\eta,k) e^{-i2\pi\xi y} \ d\eta, \qquad y \in \mathbb{R}, \end{split}$$

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In the limit it decompose in a thermal and a mechanical part:

$$\lim_{N\to\infty}\widehat{W}_N(\xi,k,t) = \widehat{W}_{th}(\xi,k,t) + \widehat{W}_m(\xi,t)\,\delta_0(dk)$$
(3)

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The mechanical part $\widehat{W}_m(\xi, t)$ is the Fourier transform of the mechanical energy

$$\widehat{W}_m(\xi,t) = \int \frac{1}{2} \left(\mathbf{p}^2(y,t) + \mathbf{r}^2(y,t) \right) e^{i2\pi\xi y} \, dy,$$

For the thermal Wigner distribution it holds the transport equation:

$$\partial_t W_{th}(y,k,t) + \frac{\omega'(k)}{2\pi} \partial_y W_{th}(y,k,t) = 0.$$

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in fact for $k \neq 0$

$$\widehat{W}_{N}(\xi,k,t) := e^{i\left[\omega\left(k-\frac{\xi}{2N}\right)-\omega\left(k+\frac{\xi}{2N}\right)\right]Nt}\widehat{W}_{N}(\xi,k,0)$$
$$\underset{N\to\infty}{\sim} e^{-i\omega'(k)\xi t}\widehat{W}_{th}(\xi,k,0)$$

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$$\partial_t W_{th}(y,k,t) + \frac{\omega'(k)}{2\pi} \partial_y W_{th}(y,k,t) = 0.$$

in fact for $k \neq 0$

$$\widehat{W}_{N}(\xi,k,t) := e^{i\left[\omega\left(k-\frac{\xi}{2N}\right)-\omega\left(k+\frac{\xi}{2N}\right)\right]Nt}\widehat{W}_{N}(\xi,k,0)$$
$$\underset{N\to\infty}{\sim} e^{-i\omega'(k)\xi t}\widehat{W}_{th}(\xi,k,0)$$

$$W(t,y,k) = W(0,y - \frac{\omega'(k)}{2\pi}t,k)$$

Phonon of wave number k moves freely with velocity $\frac{\omega'(k)}{2\pi}$.

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Consequently the thermal energy $\tilde{\mathbf{e}}(y,t)$ (i.e. temperature) evolves non autonomously following the equation

$$\partial_t \tilde{\mathbf{e}}(y,t) + \partial_y J(y,t) = 0, \qquad J(y,t) = \int \omega'(k) W_{th}(y,k,t) \, dk.$$

We say that the system is in *local equilibrium* if $W_{th}(y,k) = \beta^{-1}(y)$ constant in k. Starting in thermal equilibrium means $W_{th}(y,k,0) = \beta^{-1}$ and trivially $W_{th}(y,k,t) = \beta^{-1}$ for any t > 0. But starting with local equilibrium, i.e. $W(y,k,0) = \beta^{-1}(y)$ constant in k, we have a non autonomous evolution of $\tilde{e}(y,t)$.

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The problem with the harmonic chain is that thermal waves of wavenumber k move with speed $\omega'(k)$, if they are not uniformed distributed (i.e. the system is not in thermal equilibrium), the temperature profile will not remain constant, as it should be following the Euler equations.

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If the masses are random, the thermal modes remains localized (frozen), by Anderson localization. This allows to close the energy equation, without local equilibrium.

(F. Huveneers, C. Bernardin, S.Olla, 2017) $\{m_x\}$ i.i.d. with absolutely continuous distribution, $0 < m_- \le m_x \le m_+,$ $\overline{m} = \mathbb{E}(m_x).$

 $m_x \dot{q}_x(t) = p_x(t), \qquad \dot{p}_x(t) = \Delta q_x(t), \qquad x = 1, \dots, N$

with $q_0 = q_1$ and $q_{N+1} = q_N$ as boundary conditions.

The Gibbs states are characterized by three parameters: $\beta > 0$ and $p, r \in \mathbb{R}$. Its probability density writes

$$\prod_{x=1}^{N} \frac{e^{-\frac{\beta m_x}{2} \left(\frac{p_x}{m_x}-\frac{p}{m}\right)^2-\frac{\beta}{2}(r_x-r)^2}}{Z(\beta,p,r,m_x)}.$$

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We start with a local Gibbs state:

$$\prod_{x=1}^{N} \frac{e^{-\frac{\beta(x/N)m_{x}}{2} \left(\frac{p_{x}}{m_{x}} - \frac{p(x/N)}{\overline{m}}\right)^{2} - \frac{\beta(x/N)}{2} (r_{x} - r(x/N))^{2}}}{Z(\beta(x/N), p(x/N), r(x/N), m_{x})}$$

Almost surely with respect to $\{m_x\}$:

 $< r_{[Ny]}(Nt) >, < p_{[Ny]}(Nt) >, < \mathcal{E}_{[Ny]}(Nt) > \rightarrow (\mathbf{r}(y,t), \mathbf{p}(y,t), \mathbf{e}(y,t))$ $\partial_t \mathbf{r}(t,y) = \frac{1}{\overline{m}} \partial_y \mathbf{p}(t,y)$ $\partial_t \mathbf{p}(t,y) = \partial_y \mathbf{r}(t,y)$

$$\partial_t \mathfrak{e}(t,y) = \frac{1}{\overline{m}} \partial_y \left(\mathbf{r}(t,y) \mathbf{p}(t,y) \right)$$

with initial conditions:

$$\mathbf{r}(y,0) = r(y),$$
 $\mathbf{p}(y,0) = p(y),$ $\mathbf{e}(y,0) = \frac{1}{\beta(y)} + \frac{p^2(y)}{2\overline{m}} + \frac{r^2(y)}{2}.$

Random Masses: Localization of Thermal Modes

Equation of motion can be written as

 $\ddot{r}_{x} = -(\nabla^{*}M^{-1}\nabla r)_{x} \quad (1 \le x \le N-1), \qquad \ddot{p}_{x} = (\Delta M^{-1}p)_{x} \quad (1 \le x \le N),$

where $M_{x,x'} = \delta_{x,x'} m_x$.

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where $M_{x,x'} = \delta_{x,x'} m_x$.

$$M^{-1/2}(-\Delta)M^{1/2}\varphi^k = \omega_k^2 \varphi^k, \qquad k = 0, \dots, N-1.$$

$$\psi^{k} = M^{-1/2} \varphi^{k}, \qquad M^{-1} \Delta \psi^{k} = \omega_{k}^{2} \psi_{k}$$

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$$r(t) = \sum_{k=1}^{N-1} \left(\frac{\langle \nabla \psi^k, r(0) \rangle}{\omega_k} \cos \omega_k t + \langle \psi^k, p(0) \rangle \sin \omega_k t \right) \frac{\nabla \psi^k}{\omega_k},$$

$$p(t) = \sum_{k=0}^{N-1} \left(\langle \psi^k, p(0) \rangle \cos \omega_k t - \frac{\langle \nabla \psi^k, r(0) \rangle}{\omega_k} \sin \omega_k t \right) M \psi^k.$$

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Localization length ξ_k diverges with N:

$$\xi_k^{-1} ~\sim~ \omega_k^2 ~\sim~ \left(\frac{k}{N}\right)^2,$$

only the modes $k > \sqrt{N}$ are localized.

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only the modes $k > \sqrt{N}$ are localized. More precisely: for $0 < \alpha < \frac{1}{2}$

$$\mathbb{E}\left(\sum_{k=N^{1-\alpha}}^{N-1} |\psi_x^k \psi_{x'}^k|\right) \leq C e^{-cN^{-2\alpha}|x-x'|}.$$

This estimate is enough to prove that thermal modes remains localized and do not *move* macroscopically.

Assume for simplicity that we are in a mechanical equilibrium:

$$\langle r_x(0) \rangle = 0, \qquad \langle p_x(0) \rangle = 0,$$

(only thermal energy present) but not in thermal equilibrium, then, for any $\alpha \ge 1$

$$< \mathcal{E}_{[Ny]}(N^{\alpha}t) > \underset{N \ to\infty}{\longrightarrow} \mathbf{e}(0,y) = \overline{C}(\beta(y))$$

NO evolution for the temperature profile at any scale!

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NO evolution for the temperature profile at any scale! In particular, for $\alpha = 2$ (diffusive scaling), thermal diffusivity is null. In order to deal with the anharmonic interaction, in the classical case, conservative noise is added to obtain ergodicity of the infinite dynamics (unique characterization of the translational invariant stationary states)
 (cf B. Nachtergaele, and H-T Yau, CMP 2003).
 How to add *conservative noise* in the quantum dynamics in order to obtain similar result?

- In order to deal with the anharmonic interaction, in the classical case, conservative noise is added to obtain ergodicity of the infinite dynamics (unique characterization of the translational invariant stationary states)
 (cf B. Nachtergaele, and H-T Yau, CMP 2003).
 How to add *conservative noise* in the quantum dynamics in order to obtain similar result?
- Boundary tension? More generally boundary conditions, thermostat etc.

$$\partial_t r = \partial_x p \qquad \partial_t p = \partial_x \tau \qquad \partial_t \mathfrak{e} = \partial_x (\tau p)$$
$$p(t,0) = 0, \qquad \tau(r(1,t), u(1,t)) = \tau(t)$$

$$U = \mathfrak{e} - p^2/2, \ \beta = \frac{\partial S}{\partial U}, \ \tau = -\frac{1}{\beta} \frac{\partial S}{\partial r}$$

$$\begin{array}{ccc} \partial_t r = \partial_x p & \partial_t p = \partial_x \tau & \partial_t \mathfrak{e} = \partial_x (\tau p) \\ \rho(t, 0) = 0, & \tau(r(1, t), u(1, t)) = \tau(t) \end{array}$$

$$U = \mathfrak{e} - p^2/2, \ \beta = \frac{\partial S}{\partial U}, \ \tau = -\frac{1}{\beta} \frac{\partial S}{\partial r}$$

For smooth solutions:

$$\frac{d}{dt}S(u(y,t),r(y,t)) = \beta (\partial_t e - p\partial_t p) - \beta \tau \partial_t r$$
$$= \beta (\partial_x(\tau p) - p\partial_x \tau - \tau \partial_x p) = 0$$

The evolution is *isoentropic* in the smooth regime.

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Shocks, contact discontinuities, weak solutions, entropy solutions

Even starting with initial smooth profiles, hyperbolic non-linear systems develops discontinuities:

shocks: discontinuities in the tension profile,

- shocks: discontinuities in the tension profile,
- contact discontinuities: discontinuities in the entropy profile.

When this happens we have to consider *weak solution*, that typically are not unique.

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In order to select the *right physical solutions*, various properties (maybe equivalent) have been introduced:

- entropy solutions
- viscosity solutions

Consider a hyperbolic system of conservation laws

$$v_t + f(v)_x = 0,$$

a weak solution v(t, y) on an open set $\Omega \subset \mathbb{R}^2$ satisfies, for any function $\phi(t, y) \in \mathcal{C}^1$ with compact support in Ω

$$\iint_{\Omega} \left[\phi_t v + \phi_y f(v) \right] dy \ dt = 0$$

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No continuity assumption is made on v.

In the Euler case, v = (r, p, e), $u = e - p^2/2$ and

$$f(v) = -\begin{pmatrix} p\\ \tau(u,r)\\ p\tau(u,r) \end{pmatrix}$$

Strictly Hyperbolic System: the Jacobian matrix *Df* has real distinct eigenvalues.
A weak solution of

$$v_t + f(v)_x = 0,$$
 $v(0, y) = v_0(y),$

is a weak solution of the Cauchy initial data problem if $t \in [0, T] \rightarrow v(t, \cdot)$ is continuous in \mathcal{L}^{1}_{loc} . A weak solution of

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is a weak solution of the Cauchy initial data problem if $t \in [0, T] \rightarrow v(t, \cdot)$ is continuous in L^1_{loc} .

unfortunately it may not be unique!

Existence proved only for v_0 of bounded variation (Glimm,....).

Entropic weak solutions

$$v_t + f(v)_x = 0,$$
 $v(0, y) = v_0(y),$ $v(t, y) \in \mathbb{R}^n$

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- n = 1: any convex non-linear η is an *entropy function*,
- $n \ge 3$: ? It may nont exists
- For the Euler System: the thermodynamic entropy $\eta(v) = S(e p^2/2, r)$ is an *entropy function*.

 $v_t + f(v)_x = 0,$ $v(0, y) = v_0(y),$ $v(t, y) \in \mathbb{R}^n$ An weak solution is *entropy-admissible* if $\eta(v)_t + q(v)_x \le 0$ as distribution, for *any* entropy pair (η, q) .

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as distribution, for *any* entropy pair (η, q) . This implies that total entropy $\int \eta(v(t, y))dy$ increase in time (with no b.c. here). Existence is proven only under *bounded variation* initial conditions.

The conjecture is that entropy-admissible solutions are *unique*.

$$v_t^{\varepsilon} + f(v^{\varepsilon})_X = \varepsilon v_{XX}^{\varepsilon},$$

or more general

$$v_t^{\varepsilon} + f(v^{\varepsilon})_x = \varepsilon \Lambda(v^{\varepsilon}),$$

where Λ is a second order differential operator (eventually non-linear).

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If v^{ε} converges in L^1_{loc} as $\varepsilon \to 0^+$, this is called a *vanishing viscosity* solution.

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If v^{ε} converges in L^{1}_{loc} as $\varepsilon \to 0^{+}$, this is called a *vanishing viscosity* solution.

Bianchini-Bressan (AoM, 2005): if initial data are of small BV, limit exists unique and is BV and is an entropy solution, (for linear viscosity).

J. Fritz, *Microscopic theory of isothermal elasticity*, ARMA 2011, infinite volume

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- J. Fritz, *Microscopic theory of isothermal elasticity*, ARMA 2011, infinite volume
- S. Marchesani, S. Olla, Nonlinearity 2018, boundary conditions.

The system is in contact with a heat bath that keeps it at a constant temperature β^{-1} .

Energy is not conserved anymore. Macroscopically we have a p-system:

$$\partial_t r(t, y) = \partial_y p(t, y)$$
$$\partial_t p(t, y) = \partial_y \tau[\beta, r(t, y)]$$

MIcroscopic isothermal dynamics



$$\begin{cases} dr_{1} = Np_{1}dt + N\sigma_{N} \left(V'(r_{2}) - V'(r_{1}) \right) dt - \sqrt{2\beta^{-1}N\sigma_{N}} d\widetilde{w}_{1} \\ dr_{i} = N(p_{i} - p_{i-1})dt + N\sigma_{N} \left(V'(r_{i+1}) + V'(r_{i-1}) - 2V'(r_{i}) \right) dt + \sqrt{2\beta^{-1}N\sigma_{N}} (d\widetilde{w}_{i-1} - d\widetilde{w}_{i}) \\ dr_{N} = N(p_{N} - p_{N-1})dt + N\sigma_{N} \left(V'(r_{N-1}) - V'(r_{N}) \right) dt + \sqrt{2\beta^{-1}N\sigma} d\widetilde{w}_{N-1} \\ dp_{1} = N(V'(r_{2}) - V'(r_{1}))dt + N\sigma_{N} \left(p_{2} - p_{1} \right) dt - \sqrt{2\beta^{-1}N\sigma_{N}} dw_{1} \\ dp_{i} = N(V'(r_{i+1}) - V'(r_{i})) dt + N\sigma_{N} \left(p_{i+1} + p_{i-1} - 2p_{i} \right) dt + \sqrt{2\beta^{-1}N\sigma_{N}} (dw_{i-1} - dw_{i}) \\ dp_{N} = N(\overline{\tau}(t) - V'(r_{N})) dt + N\sigma_{N} \left(p_{N-1} - p_{N} \right) dt + \sqrt{2\beta^{-1}N\sigma_{N}} dw_{N-1}, \end{cases}$$

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$$\lim_{N \to +\infty} \frac{\sigma_N}{N} = \lim_{N \to \infty} \frac{N}{\sigma_N^2} = 0.$$

Isothermal dynamics, generator

$$\begin{aligned} \mathcal{G}_{N}^{\bar{\tau}(t)} &:= N L_{N}^{\bar{\tau}(t)} + N \sigma_{N} (S_{N} + \tilde{S}_{N}). \\ L_{N}^{\bar{\tau}(t)} &= \sum_{i=1}^{N} (p_{i} - p_{i-1}) \partial_{r_{i}} + \sum_{i=1}^{N-1} \left(V'(r_{i+1}) - V'(r_{i}) \right) \partial_{p_{i}} + (\bar{\tau}(t) - V'(r_{N})) \partial_{p_{N}}, \end{aligned}$$

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Isothermal dynamics, generator

$$\mathcal{G}_{N}^{\bar{\tau}(t)} := NL_{N}^{\bar{\tau}(t)} + N\sigma_{N}(S_{N} + \tilde{S}_{N}).$$
$$L_{N}^{\bar{\tau}(t)} = \sum_{i=1}^{N} (p_{i} - p_{i-1})\partial_{r_{i}} + \sum_{i=1}^{N-1} (V'(r_{i+1}) - V'(r_{i}))\partial_{p_{i}} + (\bar{\tau}(t) - V'(r_{N}))\partial_{p_{N}},$$

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$$S_{N} := -\sum_{i=1}^{N-1} D_{i}^{*} D_{i}, \quad \tilde{S}_{N} := -\sum_{i=1}^{N-1} \tilde{D}_{i}^{*} \tilde{D}_{i},$$
$$D_{i} := \frac{\partial}{\partial p_{i+1}} - \frac{\partial}{\partial p_{i}}, \qquad D_{i}^{*} := p_{i+1} - p_{i} - \beta^{-1} D_{i}$$
$$\tilde{D}_{i} := \frac{\partial}{\partial r_{i+1}} - \frac{\partial}{\partial r_{i}}, \qquad \tilde{D}_{i}^{*} := V'(r_{i+1}) - V'(r_{i}) - \beta^{-1} \tilde{D}_{i}.$$

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Initial distribution

The density f_t^N with respect to $\mu^N = \mu^N_{\beta,0,0}$ solves the Fokker-Plank equation

$$\frac{\partial f_t^N}{\partial t} = \left(\mathcal{G}_N^{\bar{\tau}(t)}\right)^* f_t^N.$$

Here $(\mathcal{G}_{N}^{\bar{\tau}(t)})^{*} = -NL_{N}^{\bar{\tau}(t)} + N\bar{\tau}(t)p_{N} + N\sigma(S_{N} + \tilde{S}_{N})$ is the adjoint of $\mathcal{G}_{N}^{\bar{\tau}(t)}$ with respect to μ^{N} .

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relative entropy

$$H_N(f_t^N) \coloneqq \int_{\mathbb{R}^{2N}} f_t^N \log f_t^N d\mu^N$$

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relative entropy

$$H_N(f_t^N) \coloneqq \int_{\mathbb{R}^{2N}} f_t^N \log f_t^N d\mu^N$$

assume or the initial distribution

$$H_N(f_0^N) \leq CN.$$

Limite Hydrodynamique

$$\frac{1}{N}\sum_{x}G(x/N)\begin{pmatrix} r_{x}(t)\\ p_{x}(t) \end{pmatrix} \xrightarrow[N \to \infty]{} \int_{0}^{1}G(y)\begin{pmatrix} r(y,t)\\ p(y,t) \end{pmatrix} dy$$

 L^2 -valued weak solution of

$$\begin{split} \partial_t r(t,y) &= \partial_y p(t,y) \\ \partial_t p(t,y) &= \partial_y \tau_\beta [r(t,y)] \\ p(t,0) &= 0, \quad \tau(r(t,1)) = \bar{\tau}(t), \end{split}$$

in the sense

$$\int_0^\infty \int_0^1 (r(t,x)\partial_t \varphi(t,x) - p(t,x)\partial_x \varphi(t,x)) \, dx \, dt = 0$$
$$\int_0^\infty \int_0^1 (p(t,x)\partial_t \psi(t,x) - \tau_\beta(r(t,x))\partial_x \psi(t,x)) \, dx \, dt = 0$$

for all functions φ, ψ with compact support on $\mathbb{R}_+ \smallsetminus \{0\} \times (0, 1)$. NO information on initial and boundary conditions, no entropy condition. The heat bath interaction in the dynamics plays the role of a *microscopic viscosity*, vanishing in the macroscopic limit.

The heat bath interaction in the dynamics plays the role of a *microscopic viscosity*, vanishing in the macroscopic limit. The corresponding viscous equations would be:

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with boundary conditions

$$p^{\varepsilon}(t,0) = 0, \quad \tau(r^{\varepsilon}(t,1)) = \overline{\tau}(t), \quad \partial_{x}p^{\varepsilon}(t,1) = 0, \quad \partial_{x}r^{\varepsilon}(t,0) = 0,$$

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Note the non-linear viscosity term. As $\varepsilon \rightarrow 0$ boundary layers may appear. It is usually difficult to control bounds in the vanishing viscosity $\varepsilon \rightarrow 0,$

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When boundaries are present, it is less clear how to define weak solutions that are not of BV.

One proposal would be to take L^2 limits as $\varepsilon \to 0$ of

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The non-linearity in the viscosity gives the right *entropy production*.

Entropy production and Clausius inequality

Let
$$v^{\varepsilon}(t, y) = r^{\varepsilon}(t, y), p^{\varepsilon}(t, y)$$
. Free energy at time t :

$$\mathcal{F}(v^{\varepsilon}(t)) = \int_{0}^{1} \left[\frac{p^{\varepsilon}(t, y)^{2}}{2} + F_{\beta}(r^{\varepsilon}(t, y)) \right] dy, \qquad \partial_{r}F_{\beta}(r) = \tau_{\beta}(r),$$

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$$\mathcal{F}(v^{\varepsilon}(t)) - \mathcal{F}(v(0)) = W(t) - \varepsilon \int_0^t ds \int_0^1 dy \left[\left(\partial_y \tau_\beta(r^{\varepsilon}(s,y)) \right)^2 + \left(\partial_x p^{\varepsilon}(s,y) \right)^2 \right] \geq W(t)$$

where W(t) is the work done by the boundary force $\tau(t)$. So we expect that this particular limit generates the *right* entropy solutions.

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- Hydrodynamic limit for one conserved quantity (Burgers equation) with boundary conditions have been proven by Bahadoran (from ASEP).
- There exists extention to systems of the boundary entropy condition (Chen-Frid), but with BV solutions.

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- The Fritz's approach that we use is based on a stochastic version of the compensated compactness lemma of Tartar-Murat. This was used by Di Perna to prove existence of vanishing viscosity limits in p-systems.
- This is a trick to prove that weak limit of viscous solutions v^{ve} are actually strong limit, which is also the main problem in hydrodynamic limits from microscopic dynamics.
- Unfortunately the trick works only when one has many (at least two) entropy pairs $((\eta_1, q_1), (\eta_2, q_2))$. This restrict the trick to 2x2 systems of conservation law, cannot be used for the Euler equation 3x3, where we know only the thermodynamic entropy as *mathematical entropy*.

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$$\eta_j(v^\varepsilon)_t+q_j(v^\varepsilon)_x\in \text{compact set in}H^{-1},\qquad j=1,2$$
 then

$$\eta_1(v^{\varepsilon})q_2(\varepsilon^{\varepsilon}) - \eta_2(v^{\varepsilon})q_1(v^{\varepsilon}) \qquad \text{converge weakly in } L^{\infty},$$

and this is enough to establish the strong convergence of v^{ε} .